Stationary Measures for Stochastic Lotka-Volterra Systems with Application to Turbulent Convection

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Ergodic Properties of Stochastic L-V System

Motivation: Mathematical Formulation

• Turbulent convection in a fluid layer heated from below and rotating about a vertical axis was studied by Busse et al, (Science, 1980; Nonl. Dyn., 1980).



• The convection model is formulated by the *Navier-Stokes* equations for the velocity vector \mathbf{v} and the heat equation for the deviation θ of the temperature from the static state:

Motivation: Mathematical Formulation

$$\begin{cases} P^{-1}(\frac{\partial}{\partial t} + \mathbf{v} \cdot \nabla)\mathbf{v} + \frac{\sqrt{T}}{2}\lambda \times \mathbf{v} = -\nabla\pi + \lambda\theta + \nabla^{2}\mathbf{v} \\ \nabla \cdot \mathbf{v} = 0 \\ (\frac{\partial}{\partial t} + \mathbf{v} \cdot \nabla)\theta = R\lambda \cdot \mathbf{v} + \nabla^{2}\theta \end{cases}, \quad (1.1)$$

 $\begin{array}{l} \lambda: \quad \text{The unit vector in the vertical direction;} \\ R = \frac{g\gamma(T_2 - T_1)d^3}{\kappa\nu}: \quad \text{the Rayleigh number;} \\ T = \frac{4\Omega^2 d^4}{\nu^2}: \quad \text{the Taylor number;} \quad P = \frac{\nu}{\kappa}: \quad \text{the Prandtl number.} \\ \bullet \quad \text{Then time-dependent amplitude } C_i(t) \text{ satisfies L-V equation:} \end{array}$

$$M\frac{dC_i}{dt} = C_i \{ (\mathbf{R} - \mathbf{R}_c)\mathbf{K} - \frac{1}{2} \sum_{j=-n}^n T_{ij} \mid C_j \mid^2 \}.$$

Motivation

• It is demonstrated by experiments: when the Rayleigh number R exceeds the critical value R_c depending on the Taylor number T, the static state becomes unstable and convective motions set in.

• Let
$$n = 3$$
, setting $S_i = |C_i|^2$.

Special case — standard symmetric May-Leonard system:

$$\begin{cases} \frac{dS_1}{dt} = S_1(1 - S_1 - \alpha S_2 - \beta S_3), \\ \frac{dS_2}{dt} = S_2(1 - \beta S_1 - S_2 - \alpha S_3), \\ \frac{dS_3}{dt} = S_3(1 - \alpha S_1 - \beta S_2 - S_3), \end{cases}$$
(1.2)

with $\alpha, \beta > 0$.

The possible equilibrium solutions of (1.2) as points: $\diamondsuit O(0,0,0)$; $\heartsuit 3$ single-species solutions of the form (1,0,0); $\clubsuit 3$ two-species solutions of the form $(1-\alpha, 1-\beta, 0)/(1-\alpha\beta)$; \clubsuit the three-species equilibrium $(1,1,1)/(1+\alpha+\beta)$.

The eigenvalues $\lambda_i \ (i=1,2,3)$ of the three-species equilibrium's matrix can be written down

$$\lambda_1 = -1 - (\alpha + \beta), \quad \lambda_{2,3} = -1 + \frac{(\alpha + \beta)}{2} \pm \frac{\sqrt{3}}{2} (\alpha - \beta)i.$$

- This equilibrium is stable if $\alpha + \beta \leq 2$; It is asymptotical stable if and only if $\alpha + \beta < 2$.
- It is unstable if $\alpha + \beta > 2$.

Stability Properties of (1.2) as a Function of α and β



Figure: In the domain (a) the stable equilibrium point is that with all three populations present; in the domain (b) the 3 single-species equilibrium points (1,0,0), (0,1,0) and (0,0,1) are all stable, and which one the system converges to depends on the initial conditions; in the domain (c) there is no asymptotically stable equilibrium point, and periodic solutions, as well.

Periodic Orbit: $\alpha + \beta = 2$



Figure: The global phase portraits for a system (1.2) with $\alpha + \beta = 2$.

Statistical Limit Cycle: $\alpha + \beta > 2$

• Statistical limit cycle occurs ((1.2) with $\alpha + \beta > 2$):



Figure: 2. The development in time of the three roll orientations in the absence of a low level noise source.

Motivation

• Heikes and Busse (Nonl. Dyn., 1980) showed that the randomness occurs for Rayleigh number R close to the critical value for the onset of convection, R_c .

• They expected that the transition from one set of rolls (stationary solutions) to the next becomes nearly periodic, with a transition time which fluctuates statistically about a mean value.

• This stimulates us to exploit that whether stochastic version of cyclically fluctuating solution (limit cycle) exists when $R - R_c$ is perturbed by a white noise ——

$$(R-R_c)+\sigma B_t,$$

where B is a Brownian motion.

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Stochastic Lotka-Volterra Systems

We consider the perturbed system

$$(\mathbf{E}_{\sigma}): dy_{i} = y_{i}(r + \sum_{j=1}^{n} a_{ij}y_{j})dt + \sigma y_{i} \circ dB_{t}, \ i = 1, 2, ..., n$$

on the positive orthant \mathbf{R}^n_+ , where $r = (R - R_c)K$, $a_{ij} = -T_{ij}$ and σ are parameters, \circ denotes Stratonovich stochastic integral.

Stochastic Decomposition Formula

• Auxiliary equation (1-D Stochastic Logistic equation)

$$dg = g(r - rg)dt + \sigma g \circ dB_t.$$
(2.1)

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The following theorem play an important role to analysis the ergodic properties of equation $(E_{\sigma}).$

Theorem 1 (Stochastic Decomposition Formula)

Let $\Phi(t, \omega, y)$ and $\Psi(t, y)$ be the solutions of (E_{σ}) and (E_{0}) , respectively. Then

$$\Phi(t,\omega,y) = g(t,\omega,g_0)\Psi(\int_0^t g(s,\omega,g_0)ds,\frac{y}{g_0}), \ y \in \mathbf{R}^n_+, \ g_0 > 0,$$
(2.2)
where $g(t,\omega,g_0)$ is a positive solution of the Logistic equation
(2.1).

• Of course, the same conclusion (2.2) remains true, if we understand the stochastic equation (E_{σ}) and (2.1) in the *ltô sense*. Also, the result given above remain true for all $a_{ij} \in \mathbf{R}$.

• In following, we only pay attention to Stratonovitch stochastic integral, since Stratonovitch stochastic integral has some simplifications in formulas. Also, there is a simple relation between the Itô and Stratonovich cases.

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Intuition

Stochastic Chaos in Trajectory.

From the Stochastic Decomposition Formula it follows that

$$\Phi(t, \theta_{-t}\omega, y) = g(t, \theta_{-t}\omega, 1)\Psi(\int_0^t g(s, \theta_{-t}\omega, 1)ds, y).$$

$$\downarrow \qquad \qquad \downarrow \qquad \qquad \downarrow$$

$$u(\omega) \qquad \qquad \text{chaos}$$

Here u is an an *equilibrium* (or *stationary solution*) of RDS generated by (2.1).

• Roughly speaking, that *complexity* of the deterministic case which describes the stochastic case.

The Complete Classification for 3-Dim Stochastic L-V System

In this section we focus on three dimensional stochastic $\mbox{L-V}$ system:

$$dy_1 = y_1(r - a_{11}y_1 - a_{12}y_2 - a_{13}y_3)dt + \sigma y_1 \circ dB_t,$$

$$dy_2 = y_2(r - a_{21}y_1 - a_{22}y_2 - a_{23}y_3)dt + \sigma y_2 \circ dB_t, \quad (3.0)_\sigma$$

$$dy_3 = y_3(r - a_{31}y_1 - a_{32}y_2 - a_{33}y_3)dt + \sigma y_3 \circ dB_t.$$

Here $r > 0, a_{ij} > 0, i, j = 1, 2, 3.$

• We deal with $a_{ij} > 0$ only, in this case the system $(3.0)_{\sigma}$ is called *competitive*. However several results given below remain true for all $a_{ij} \in \mathbf{R}$.

• When $\sigma = 0$, the above system $(3.0)_0$ becomes **deterministic** competitive *L-V* system, which can be classified by the parameters a_{ij} .

Theorem 2 (Chen, Jiang and Niu, SIADS, 2015)

There are exactly 37 dynamical classes in 33 stable nullcline classes for deterministic system $(3.0)_0$.

(1) All trajectories tend to equilibria for classes 1-25, 26 a), 26 c), 27 a) and 28-33;

(2) a center on Σ only occurs in 26 b) and 27 b);

(3) the heteroclinic cycle attracts all orbits except ray-L(P) in class 27 c).

All are depicted on Σ (called carrying simplex—see, Hirsch, 1988) and presented in following Figure.

Introduction Stochastic Decomposition Formula The Complete Classification for 3-Dim Stochastic L-V System

The Classification via Stationary Measures Ergodic Properties of Stochastic L-V System



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- $L(P) := \{\lambda P : \lambda \ge 0\}$ for any $P \in \mathbf{R}^3_+ \setminus \{O\}$;
- \mathcal{E} : the equilibrium set for $(3.0)_0$;
- $\mathcal{A}(Q)$: the attracting domain for an equilibrium $Q \in \mathcal{E}$;
- P(t, y, A): the transition probability function is defined by

 $P(t, y, A) := \mathbb{P}(\Phi(t, \omega, y) \in A).$

Theorem 3

Let $Q \in \mathcal{E} \setminus \{O\}$, then $\mu_Q^{\sigma}(A) = \mathbb{P}(U \in A)$ is a stationary measure of semigroup $\{P_t\}_{t \geq 0}$, where $U(\omega) := u(\omega)Q$. Furthermore, (i) for each $y \in \mathcal{A}(Q)$, $P(t, y, \cdot) \xrightarrow{w} \mu_Q^{\sigma}$ as $t \to \infty$, and

$$\lim_{t \to \infty} P(t, y, A) = \mu_Q^{\sigma}(A), \text{ for any } A \in \mathcal{B}(\mathbf{R}^3_+).$$
(3.1)

Hence, it is **ergodic** when the system is restricted on $\mathcal{A}(Q)$. (ii) $\mu_Q^{\sigma}(\cdot) \xrightarrow{w} \delta_Q(\cdot)$ as $\sigma \to 0$. These results are available for classes 1-25, 26 a), 26 c), 27 a) and 28-33 when we restrict the state space in its stable manifold.

The Classification via Stationary Measures Ergodic Properties of Stochastic L-V System

The Complete Classification via Stationary Measures

Theorem 4

Suppose that $(3.0)_0$ is one of systems in classes 1-25, 26 a), 26 c), 27 a) and 28-33. Then (1) all its stationary measures are the convex combinations of ergodic stationary measures $\{\mu_Q^{\sigma} : Q \in \mathcal{E}\};$ (2) as $\sigma \to 0$, all their limiting measures are the convex combinations of the Dirac measures $\{\delta_Q(\cdot) : Q \in \mathcal{E}\}.$

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Recall the following dynamical classes (red—Periodic case and green—Heterclinic case).



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Theorem 5

Suppose that $(3.0)_0$ is one of systems in classes 26 b) and 27 b). (1) Then there exists a unique **ergodic** nontrivial stationary measure ν_h^{σ} supporting on the cone

$$\Lambda(h): V(y) := y_1^{\mu} y_2^{\nu} y_3^{\omega}(\beta_2 \alpha_3 y_1 + \alpha_1 \alpha_3 y_2 + \beta_1 \beta_2 y_3) \equiv h \in I,$$
 (3.2)

where $\mu = -\beta_2\beta_3/D$, $\nu = -\alpha_1\alpha_3/D$, $\omega = -\alpha_1\beta_2/D$, $D = (\beta_2\beta_3 + \beta_2\alpha_1 + \alpha_1\alpha_3)$, α_i, β_i are expressed by a_{ij} , I is the feasible image interval for V and $\Gamma(h)$ is the closed orbit, with initial data $y_0 \in \Gamma(h)$. (2) ν_h^{σ} converges weakly to the Haar measure on the closed orbit $\Gamma(h)$ as $\sigma \to 0$.

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Sketch of Proof

Define
$$\psi: \ \Lambda(h) \setminus \{O\} \to \mathbf{R} \times S$$
 by

$$\psi(y) := \left(\ln \lambda, \ \varphi(z) \right), \ y \in \Lambda(h) \setminus \{O\},$$

where $\varphi(y) = \inf\{t > 0, \ \Psi(t, y_0) = y\}$. Obviously, ψ is a homeomorphism. Set

$$H(t, \omega, H_0) = \ln(g(t, \omega, \lambda))$$
 and $T(t, \omega, T_0) = \varphi(\Psi(\int_0^t g(s, \omega, \lambda) ds, z)).$

By the definition,

$$\psi(\Phi(t,\omega,y)) = \Big(H(t,\omega,H_0), \ T(t,\omega,T_0)\Big).$$

The ergodicity for Φ on $\Lambda(h) \setminus \{O\}$ is equivalent to that (H,T) is ergodic on $\mathbf{R} \times S$.

Sketch of Proof

We can prove that (H,T) is strong Feller(SF) and irreducible(I) on $\mathbf{R}\times S,$ this is

(SF) For any
$$t > 0$$
, and $F \in \mathcal{B}_b(\mathbf{R} \times S)$,

 $(H_0, T_0) \in \mathbf{R} \times S \to \mathbb{E}F(H(t, H_0), T(t, T_0))$ is continuous;

(1) For any $t > 0, \ (H_0, T_0) \in \mathbf{R} \times S$ and open set $A \in \mathcal{B}(\mathbf{R} \times S)$,

$$\mathbb{P}\Big((H(t,H_0),T(t,T_0))\in A\Big)>0.$$

Sketch of Proof

This implies that Φ is ergodic on $\Lambda(h) \setminus \{O\}$. Furthermore, Φ is also ergodic on $\Lambda(h)$ and ν_h^{σ} is an ergodic stationary measure for Φ on \mathbf{R}^3_+ . Finally, ν_h^{σ} converges weakly to the Haar measure on the closed orbit $\Gamma(h)$ as $\sigma \to 0$.

The Complete Classification via Stationary Measures

Theorem 6

Suppose that $(3.0)_0$ is one of systems in classes 26 b) and 27 b). Let $\mu^i := \nu_{h^i}^{\sigma^i}$, $i = 1, 2, \cdots$ satisfy $\sigma^i \to 0$ and $\mu^i \xrightarrow{w} \mu$ as $i \to \infty$. Then (1) if initial data y_0 lies in the interior of the heteroclinic cycle \mathcal{H} , then μ is the Haar measure on $\Gamma(y_0)$ for $y_0 \neq P$, or the Dirac measure $\delta_P(\cdot)$ at P for $y_0 = P$;

(2) if initial data $y_0 \in \mathcal{H}$, then

$$\mu(\{E_1, E_2, E_3\}) = 1, \tag{3.3}$$

where E_1, E_2, E_3 are three equilibria of heteroclinic cycle \mathcal{H} in class 26 b) or class 27 b).

The Complete Classification via Stationary Measures

Theorems 4–6 have given all ergodic stationary measures for all classes except class 27 c).

Theorem 7

Assume that $(3.0)_0$ is the system of class 27 c). Then (i) ν_y^{σ} will support on the three nonnegative axes for any ν_y^{σ} with $y \in \operatorname{Int} \mathbf{R}^3_+ \setminus L(P)$; (ii) Let $\mu^i := \nu_{y_0^i}^{\sigma_i^i}$, $i = 1, 2, \cdots$. If $\mu^i \xrightarrow{w} \mu$ as $\sigma^i \to 0, i \to \infty$. Then

$$\mu(\{R_1, R_2, R_3\}) = 1, \tag{3.4}$$

where R_1, R_2, R_3 are three axial equilibria for the deterministic system.

Conclusion

- Theorem 7 only describes the support of stationary measures.
- \bullet The nonergodicity can be found by the stochastic turbulence. (Why?)
- It is essential reason to reveal that solutions concentrate around R_1, R_2, R_3 very long time (approximately infinite) with probability nearly one.

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- The nonergodicity can be found by the stochastic turbulence. (Why?)
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Conclusion

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- The nonergodicity can be found by the stochastic turbulence. (Why?)
- It is essential reason to reveal that solutions concentrate around R_1, R_2, R_3 very long time (approximately infinite) with probability nearly one.

▲ We reveal the reason for this special case (WLOG, let $\alpha = 0.8$ and $\beta = 1.3$ for symmetric May-Leonard system). Let

$$A_i = \{y = (y_1, y_2, y_3) \in \Sigma : \|y - R_i\| < \frac{1}{2}\}$$

denote the neighborhood of R_i (i = 1, 2, 3). Then $\Psi(t, y)$ will enter and then depart A_i with infinite times. For $n \ge 2$, define

$$\begin{split} T_{\rm in}^1 &= &\inf\{t\geq 0, \ \Psi(t,y)\in A_1\}, & T_{\rm out}^1 &= &\inf\{t\geq T_{\rm in}^1, \ \Psi(t,y)\notin A_1\}, \\ T_{\rm in}^n &= &\inf\{t\geq T_{\rm out}^{n-1}, \ \Psi(t,y)\in A_1\}, & T_{\rm out}^n &= &\inf\{t\geq T_{\rm in}^n, \ \Psi(t,y)\notin A_1\}, \\ S_{\rm in}^1 &= &\inf\{t\geq T_{\rm out}^1, \ \Psi(t,y)\in A_3\}, & S_{\rm out}^1 &= &\inf\{t\geq S_{\rm in}^1, \ \Psi(t,y)\notin A_3\}, \\ S_{\rm in}^n &= &\inf\{t\geq S_{\rm out}^{n-1}, \ \Psi(t,y)\in A_3\}, & S_{\rm out}^n &= &\inf\{t\geq S_{\rm in}^n, \ \Psi(t,y)\notin A_3\}. \end{split}$$

Similarly, we denote by τ_{in}^n and τ_{out}^n the time entering and exiting A_2 in n-th spiral cycle (see Fig. 5).

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Figure: 5. The phase portrait of Ψ

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Deterministic Case

May and Leonard (SIAP, 1975) gave the following estimation:

$$T_{\rm out}^n - T_{\rm in}^n \simeq 0.42 T_{\rm out}^n, \ \tau_{\rm out}^n - \tau_{\rm in}^n \simeq 0.42 \tau_{\rm out}^n, \ S_{\rm out}^n - S_{\rm in}^n \simeq 0.42 S_{\rm out}^n.$$
 (3.5)

Then

$$\frac{1}{T_{\text{out}}^n} \int_0^{T_{\text{out}}^n} \delta_{\Psi(t,y)}(A_1) dt = \frac{1}{T_{\text{out}}^n} \sum_{i=1}^n (T_{\text{out}}^i - T_{\text{in}}^i) \ge \frac{T_{\text{out}}^n - T_{\text{in}}^n}{T_{\text{out}}^n} = 0.42 > 0,$$

$$\frac{1}{S_{\text{out}}^n} \int_0^{S_{\text{out}}} \delta_{\Psi(t,y)}(A_1) dt = \frac{1}{S_{\text{out}}^n} \sum_{i=1}^n (T_{\text{out}}^i - T_{\text{in}}^i) \le \frac{T_{\text{out}}^n}{S_{\text{out}}^n} \le (0.58)^2 \le 0.34.$$

This implies that the limit of occupation measure of $\Psi(t,y)$ is not unique.

Stochastic Case

For stochastic case, similarly, we analyze

$$\left\{\frac{1}{T}\int_0^T I_{A_1}\left(\Psi(\int_0^t g(s,\omega,1)ds,y)\right)dt\right\}_{T>0} \text{ as } T\to\infty.$$

Let $\epsilon = 0.0001$ and $\Omega_T^{\epsilon} = \{\omega : \sup_{t \in [T,\infty)} |\frac{1}{t} \int_0^t g(s,\omega,1)ds - 1| \le \epsilon\}$. Then $\Omega_T^{\epsilon} \uparrow$ with respect to T and $\lim_{T \to \infty} \mathbb{P}(\Omega_T^{\epsilon}) = 1$. Thus for $\eta = 0.9999$,

there exists $T_0 > 0$ such that

$$\mathbb{P}(\Omega_T^{\epsilon}) \ge \eta, \quad \forall T \ge T_0.$$

Image: A = A

Stochastic Case

Define

$$t_1^n(\omega) := \tau(\omega, T_{\text{in}}^n) := \inf\{t > 0 : \int_0^t g(s, \omega, g_0) ds > T_{\text{in}}^n\},$$

$$t_{2}^{n}(\omega) := \tau(\omega, T_{\text{out}}^{n}) := \inf\{t > 0 : \int_{0}^{t} g(s, \omega, g_{0}) ds > T_{\text{out}}^{n}\}.$$

Set $\Omega_{T_0}^n := \{\omega : t_1^n(\omega) \ge T_0\}$. Then $\Omega_{T_0}^n \uparrow$ with respect to n and $\lim_{n \to \infty} \mathbb{P}(\Omega_{T_0}^n) = 1$. Thus there exists an N_0 such that

$$\mathbb{P}(\Omega_{T_0}^n) \ge \eta, \quad \forall n \ge N_0.$$

Stochastic Case

Step 1. Let $T_n = T_{out}^n$. Consider $\frac{1}{T_n} \int_0^{T_n} I_{A_1} \left(\Psi(\int_0^t g(s, \omega, 1) ds, y) \right) dt$. For any n satisfying $n \ge N_0$ and $T_n \ge T_0$, choosing any $\omega \in \Omega_{T_0}^n \cap \Omega_{T_0}^{\epsilon}$, we have

• $(1-\epsilon)T_{\text{out}}^n = (1-\epsilon)T_n \leq \int_0^{T_n} g(s,\omega,1)ds \leq (1+\epsilon)T_n = (1+\epsilon)T_{\text{out}}^n$

•
$$t_2^n(\omega) \ge t_1^n(\omega) \ge T_0$$
,

• $(1-\epsilon)t_1^n(\omega) \leq \int_0^{t_1^n(\omega)} g(s,\omega,1)ds = T_{\mathrm{in}}^n \leq (1+\epsilon)t_1^n(\omega)$,

•
$$(1-\epsilon)t_2^n(\omega) \leq \int_0^{t_2^n(\omega)} g(s,\omega,1)ds = T_{\text{out}}^n \leq (1+\epsilon)t_2^n(\omega).$$

Combining the fact that $T_{\rm out}^n-T_{\rm in}^n\simeq 0.42 T_{\rm out}^n$, we have

$$t_1^n(\omega) \le T_{\text{out}}^n = T_n, \ t_2^n(\omega) \ge \frac{T_{\text{out}}^n}{1+\epsilon} = \frac{T_n}{1+\epsilon}, \ \frac{T_{\text{in}}^n}{1-\epsilon} \ge t_1^n(\omega).$$

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Stochastic Case

Continued. Therefore

$$\frac{1}{T_n} \int_0^{T_n} I_{A_1} \Big(\Psi(\int_0^t g(s,\omega,1)ds,y) \Big) dt$$
$$= \frac{1}{T_n} \sum_{i=1}^\infty \Big(t_2^i(\omega) \bigwedge T_n - t_1^i(\omega) \bigwedge T_n \Big)$$
$$\geq \frac{t_2^n(\omega) \bigwedge S_n - t_1^n(\omega)}{S_n}$$
$$\geq \frac{\frac{T_{\text{out}}^n}{1+\epsilon} - \frac{T_{\text{in}}^n}{1-\epsilon}}{T_{\text{out}}^n} \ge 0.419.$$

Then

$$\underline{\lim}_{n \to \infty} \frac{1}{T_n} \int_0^{T_n} \mathbb{E} I_{A_1} \Big(\Psi \Big(\int_0^t g(s, \omega, 1) ds, y \Big) \Big) dt$$

$$\geq 0.419 \mathbb{P} \big(\Omega_{T_0}^{N_0} \cap \Omega_{T_0}^{\epsilon} \big) \geq 0.419 \times 0.9998 \geq 0.41. \tag{3.6}$$

Stochastic Case

Step 2. Let $S_n = S_{out}^n$. Consider $\frac{1}{S_n} \int_0^{S_n} I_{A_1} \left(\Psi(\int_0^t g(s, \omega, 1), y) \right) dt$. For any n satisfying $n \ge N_0$ and $S_n \ge T_0$, choosing any $\omega \in \Omega_{T_0}^n \cap \Omega_{T_0}^{\epsilon}$, we have

•
$$(1-\epsilon)S_{\text{out}}^n = (1-\epsilon)S_n \le \int_0^{S_n} g(s,\omega,1)ds \le (1+\epsilon)S_n = (1+\epsilon)S_{\text{out}}^n$$

•
$$t_2^{n+1}(\omega) \ge t_1^{n+1}(\omega) \ge t_2^n(\omega) \ge t_1^n(\omega) \ge T_0$$
,

•
$$(1-\epsilon)t_1^i(\omega) \leq \int_0^{t_1^i(\omega)} g(s,\omega,1)ds = T_{in}^i \leq (1+\epsilon)t_1^i(\omega), \quad i=n,n+1,$$

•
$$(1-\epsilon)t_2^i(\omega) \leq \int_0^{t_2^i(\omega)} g(s,\omega,1)ds = T_{\text{out}}^i \leq (1+\epsilon)t_2^i(\omega), \quad i=n,n+1,$$

•
$$T_{\text{in}}^{n+1} \simeq S_{\text{out}}^n$$
, $S_{\text{out}}^n - S_{\text{in}}^n \simeq 0.42 S_{\text{out}}^n$, $S_{\text{in}}^n - T_{\text{out}}^n \simeq 0.42 S_{\text{in}}^n$.

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Stochastic Case

Continued. Hence

• $(1-\epsilon)t_2^n(\omega) \leq T_{\text{out}}^n \simeq 0.58S_{\text{in}}^n \simeq 0.58^2 S_{\text{out}}^n = 0.58^2 S_n \Rightarrow t_2^n(\omega) \leq S_n,$

$$\begin{split} (1-\epsilon)t_1^{n+1}(\omega) &\leq T_{\rm in}^{n+1} \simeq S_{\rm out}^n = S_n \\ &\leq \quad (1+\epsilon)t_1^{n+1}(\omega) \leq \frac{1+\epsilon}{1-\epsilon}T_{\rm in}^{n+1} \simeq 0.58\frac{1+\epsilon}{1-\epsilon}T_{\rm out}^{n+1} \\ &\leq \quad 0.58\frac{(1+\epsilon)^2}{1-\epsilon}t_2^{n+1}(\omega) < t_2^{n+1}(\omega), \end{split}$$

that is,

$$(1-\epsilon)t_1^{n+1}(\omega) \le S_n \le (1+\epsilon)t_1^{n+1}(\omega) < t_2^{n+1}(\omega).$$

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Stochastic Case

Continued. Therefore

$$\begin{aligned} \frac{1}{S_n} \int_0^{S_n} I_{A_1} \Big(\Psi \Big(\int_0^t g(s, \omega, 1) ds, y \Big) \Big) dt \\ &= \frac{1}{S_n} \sum_{i=1}^\infty \Big(t_2^i(\omega) \bigwedge S_n - t_1^i(\omega) \bigwedge S_n \Big) \\ &= \frac{1}{S_n} \Big[\sum_{i=1}^n \Big(t_2^i(\omega) - t_1^i(\omega) \Big) + \Big(S_n - t_1^{n+1}(\omega) \bigwedge S_n \Big) \Big] \\ &\leq \frac{t_2^n(\omega) + S_n - t_1^{n+1}(\omega) \bigwedge S_n}{S_n} \\ &\leq \frac{1}{S_n} \Big(\frac{0.58^2}{1 - \epsilon} S_n + S_n - \frac{S_n}{1 + \epsilon} \Big) \\ &= \frac{0.58^2}{1 - \epsilon} + \frac{\epsilon}{1 + \epsilon} < 0.34. \end{aligned}$$

Stochastic Case

Continued. Then

$$\overline{\lim}_{n\to\infty} \frac{1}{S_n} \int_0^{S_n} \mathbb{E}I_{A_1} \Big(\Psi(\int_0^t g(s,\omega,1)ds,y) \Big) dt$$

$$\leq 0.34 \mathbb{P}(\Omega_{T_0}^{N_0} \cap \Omega_{T_0}^{\epsilon}) + \mathbb{P}\Big((\Omega_{T_0}^{N_0} \cap \Omega_{T_0}^{\epsilon})^c \Big) \leq 0.342.$$
(3.7)

Inequalities (3.6) and (3.7) imply that $\frac{1}{T} \int_0^T \mathbb{E} I_{A_1} \Big(\Psi(\int_0^t g(s, \omega, 1), y) \Big) dt$ does not have unique limit as $T \to \infty$. Equivalently, $\frac{1}{T} \int_0^T \mathbb{E} I_{\Lambda(A_1)} \Big(\Phi(t, \omega, , y) \Big) dt$ does not have unique limit as $T \to \infty$.

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Thank you!