# Approximation of Invariant Measures for Regime-Switching Diffusions

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- Summary

- A regime-switching diffusion process (RSDP), is a diffusion process in random environments characterized by a Markov chain.
- The state vector of a RSDP is a pair  $(X_t, \Lambda_t)$ , where  $\{X_t\}_{t\geq 0}$  satisfies a stochastic differential equation (SDE)

$$dX_t = b(X_t, \Lambda_t)dt + \sigma(X_t, \Lambda_t)dW_t, \quad t > 0,$$
(1)

with the initial data  $X_0 = x \in \mathbb{R}^n$ ,  $\Lambda_0 = i \in \mathbb{S}$ , and  $\{\Lambda_t\}_{t \ge 0}$  denotes a continuous-time Markov chain with the state space  $\mathbb{S} := \{1, 2 \cdots, N\}$ ,

 $1\leq N\leq\infty,$  and the transition rules specified by

$$\mathbb{P}(\Lambda_{t+\triangle} = j | \Lambda_t = i) = \begin{cases} q_{ij} \triangle + o(\triangle), & i \neq j, \\ 1 + q_{ii} \triangle + o(\triangle), & i = j. \end{cases}$$
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## Motivations (Cont.)

- RSDPs have considerable applications in e.g. control problems, storage modeling, neutral activity, biology and mathematical finance (see e.g. the monographs by Mao-Yuan (2006), and Yin-Zhu (2010)).
- The dynamical behavior of RSDPs may be markedly different from diffusion processes without regime switchings, see e.g. Pinsky -Scheutzow (1992), Mao-Yuan (2006).
- So far, the works on RSDPs have included ergodicity (Cloez-Hairer (2013), Shao (2014)) stability (Mao-Yuan (06), Xi-Yin (2010)), recurrence and transience (Pinsky-Scheutzow (1992), Shao-Xi (2014), Yin-Zhu (2010)), invariant densities (Mattingly et al. (2014)), hypoellipticity (Bakhtin (2012)), and so forth

- Since solving RSDPs is still a challenging task, numerical schemes and/or approximation techniques have become one of the viable alternatives (see e.g. Mao-Yuan (2006), Yin-Zhu (2010), Higham et al. (2007)).
- For more details on numerical analysis of diffusion processes without regime switching, please refer to the monograph by Kloeden and Platen (1992).
- Also, approximations of invariant measures for stochastic dynamical sysytems have attracted much attention, see e.g. Mattingly et al. (2010), Talay (1990), Bréhier (2014).

## Motivations (Cont.)

- For the counterpart associated with Euler-Maruyama (EM) algorithms, we refer to Yuan-Mao (2005), and Yin-Zhu (2010), where RSDPs therein enjoy finite state space.
- Sufficient conditions imposed in Yuan- Mao (2005), and Yin-Zhu (2010) to guarantee existence of numerical invariant measures are irrelevant to stationary distributions of the continuous-time Markov chains.
- In this talk, we are concerned with the following questions:
- (i) Under what conditions, will the discrete-time semigroup generated by EM scheme admit an invariant measure?
- (ii) Will the numerical invariant measure, if it exists, converge in some metric to the underlying one?

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Some notation is listed as below.

- $(\Omega, \mathscr{F}, \mathbb{P})$ : probability space with a filtration  $\{\mathscr{F}_t\}_{t>0}$ ;
- $\{W_t\}_{t\geq 0}$ : an *m*-dimensional Brownian motion;
- $\{\Lambda_t\}_{t\geq 0}$ : a continuous-time Markov chain with the state space  $\mathbb{S}$  :=  $\{1, 2\cdots, N\}, N < \infty$ ; The transition rules of  $\{\Lambda_t\}_{t \ge 0}$  are specified by (2)
- Q-matrix  $Q := (q_{ij})_{N \times N}$  is irreducible and conservative so that  $\{\Lambda_t\}_{t \ge 0}$ has a unique stationary distribution  $\mu := (\mu_1, \cdots, \mu_N)$ . We assume that, in (1),  $b: \mathbb{R}^n \times \mathbb{S} \mapsto \mathbb{R}^n$  and  $\sigma: \mathbb{R}^n \times \mathbb{S} \mapsto \mathbb{R}^n \otimes \mathbb{R}^m$ satisfy the local Lipschitz condition, i.e., for each  $i \in \mathbb{S}$  and R > 0, there exists an  $L_R > 0$  such that Jianhai Bao (csu)

$$|b(x,i) - b(y,i)| + \|\sigma(x,i) - \sigma(y,i)\| \le L_R |x-y|, \quad x,y \in B_R(0).$$
 (3)

Additionally, we assume that

(H) For each  $i \in \mathbb{S}$  and  $x, y \in \mathbb{R}^n$ , there exist  $c_0 > 0$  and  $\beta_i \in \mathbb{R}$  such that

$$2\langle x, b(x,i) \rangle + \|\sigma(x,i)\|^2 \le c_0 + \beta_i |x|^2,$$
(4)

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and

$$2\langle x-y, b(x,i) - b(y,i) \rangle + \|\sigma(x,i) - \sigma(y,i)\|^2 \le \beta_i |x-y|^2.$$
(5)  
For any  $p > 0$ , let

$$\operatorname{diag}(\beta) := \operatorname{diag}(\beta_1, \cdots, \beta_N), \quad Q_p := Q + \frac{p}{2} \operatorname{diag}(\beta), \quad \eta_p := -\max_{\substack{\gamma \in \operatorname{spec}(Q_p) \\ \langle \Box \rangle \rangle \langle \Box \rangle \rangle \langle \Box \rangle \rangle \langle \Box \rangle \langle \Box$$

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where Q is the Q-matrix of  $\{\Lambda_t\}_{t\geq 0},$  and  $\operatorname{spec}(Q_p)$  denotes the spectrum of  $Q_p.$ 

(Proposition 4.2, Bardet et al. (2010)) Assume that

$$\sum_{i=1}^{N} \mu_i \beta_i < 0. \tag{7}$$

Then,  $\eta_p > 0$  for p < k, where  $k \in (0, \min_{i \in \mathbb{S}, \beta_i > 0} \{-2q_{ii}/\beta_i\})$  for  $\max_{i \in \mathbb{S}} \beta_i > 0$ . Remark:

• The RSDP (1) is said to be attractive "in average" if (7). In what follows, we call (7) an "averaging condition".

•  $\pi \in \mathcal{P}(\mathbb{R}^n \times \mathbb{S})$  is called an invariant measure of  $(X_t^{x,i}, \Lambda_t^i)$  if

$$\pi(\Gamma \times \{i\}) = \sum_{\text{Approximation of Invariant Measures for Regi}}^{N} \int_{\text{Aug., 2014}} P_t(x, j; \Gamma \times \{i\}) \pi(\mathrm{d}x \times \{j\}), \quad t \ge 0$$

(Theorem 1) Let  $N < \infty$  and assume that (3), (H) and (7) hold. Then  $(X_t^{x,i}, \Lambda_t^i)$  admits a unique invariant measure  $\pi \in \mathcal{P}(\mathbb{R}^n \times \mathbb{S})$ . Proof: The Perron-Frobenius Theorem + Proposition 4.2 (Bardet et al. (2010)).

Example I Let  $\{\Lambda_t\}_{t\geq 0}$  be a right-continuous Markov chain taking values in  $\mathbb{S}:=\{0,1\}$  with the generator

$$Q = \left(\begin{array}{rrr} -4 & 4\\ \gamma & -\gamma \end{array}\right)$$

with some  $\gamma > 0$ . Consider the scalar Ornstein-Uhlenback (O-U) process with regime switching

 $dX_t = \alpha_{\Lambda_t} X_t dt + \sigma_{\Lambda_t} dW_t, \quad t > 0, \quad X_0 = x, \quad \Lambda_0 = i_0 \in \mathbb{S}, \quad (8)$ Jianhai Bao (CSU) Approximation of Invariant Measures for Regi Aug., 2014 10 / 32

where  $\alpha_{\cdot}: \mathbb{S} \mapsto \mathbb{R}$  such that  $\alpha_0 = 1$ , and  $\alpha_1 = -1/2$ , and  $\sigma \in \mathbb{R}$  is a constant.

Remark:

- By an M-Matrix approach, (8) has a unique invariant measure for  $\gamma \in (0,1)$ , see e.g. Example 5.1 (Yuan-Mao, 2003).
- By Theorem 1,  $(X_t^{x,i}, \Lambda_t^i)$  admits a unique invariant measure  $\pi \in \mathcal{P}(\mathbb{R}^n \times \mathbb{S})$  for  $\gamma \in (0, 2)$ .
- **Theorem I** can apply more interesting examples than the existing literature.
- For a scalar RSDP, existence and uniqueness of invariant measure can be determined only by the drift coefficient in some cases.

For a given stepsize  $\delta \in (0,1)$ , define the discrete-time EM scheme associated with (1) as follows

$$\overline{Y}_{(k+1)\delta}^{x,i} := \overline{Y}_{k\delta}^{x,i} + b(\overline{Y}_{k\delta}^{x,i}, \Lambda_{k\delta}^i)\delta + \sigma(\overline{Y}_{k\delta}^{x,i}, \Lambda_{k\delta}^i) \triangle W_k, \ k \ge 0,$$
(9)

with  $\overline{Y}_0^{x,i} = x, \Lambda_0^i = i \in \mathbb{S}$ , where  $riangle W_k := W_{(k+1)\delta} - W_{k\delta}$  stands for the

Brownian motion increment. Remark:

- $(\overline{Y}^{x,i}_{k\delta},\Lambda^i_{k\delta})$  is a time homogeneous Markov chain.
- If  $\pi^{\delta} \in \mathcal{P}(\mathbb{R}^n \times \mathbb{S})$  such that

$$\pi^{\delta}(\Gamma \times \{i\}) = \sum_{j=1}^{N} \int_{\mathbb{R}^{n}} P_{k\delta}^{\delta}(x, j; \Gamma \times \{i\}) \pi^{\delta}(\mathrm{d}x \times \{j\}), \ \Gamma \in \mathscr{B}(\mathbb{R}^{n}),$$

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then we call  $\pi^{\delta} \in \mathcal{P}(\mathbb{R}^n \times \mathbb{S})$  an invariant measure of  $(\overline{Y}_{k\delta}^{x,i}, \Lambda_{k\delta}^i)_{:=}$ .

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#### Numerical Invariant Measure: Additive Noise

we further assume that, for each  $i\in\mathbb{S}$  and  $x,y\in\mathbb{R}^n,$  there exists an L>0 such that

$$b(x,i) - b(y,i)| + \|\sigma(x,i) - \sigma(y,i)\| \le L|x-y|.$$
 (10)

(Theorem 2) Let  $N < \infty$ , and assume further that (H), (7), and (10) hold with  $\sigma(\cdot, \cdot) \equiv \sigma(\cdot)$ . Then,  $(\overline{Y}_{k\delta}^{x,i}, \Lambda_{k\delta}^i)$  admits a unique invariant measure  $\pi^{\delta} \in \mathcal{P}(\mathbb{R}^n \times \mathbb{S})$  whenever the stepsize is sufficiently small. Remark:

- Example II: The EM scheme associated with (8) has a unique invariant measure whenever the stepsize δ ∈ (0, 1) is sufficiently small.
- Under the averaging condition (7), existence and uniqueness of numerical invariant measure for (1) with multiplicative noise is still open. 3900
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(i) Existence of an Invariant Measure. For each integer  $q \ge 1$ , define the measure

$$\mu_q(B_R \times \mathbb{S}) := \frac{1}{q} \sum_{k=0}^q \mathbb{P}((\overline{Y}_{k\delta}^{x,i}, \Lambda_{k\delta}^i) \in B_R \times \mathbb{S}),$$

where  $B_R := \{x \in \mathbb{R}^n : |x| \le R\}$ , a compact subset of  $\mathbb{R}^n$ , for some R > 0. To show existence of an invariant measure, it suffices to show that, for any  $x \in \mathbb{R}^n$ ,

$$\sup_{k\geq 0} \mathbb{E}|\overline{Y}_{k\delta}^{x,i}|^p < \infty.$$
(11)

Indeed, if so, the Chebyshev inequality yields that the measure sequence  $\{\mu_q(\cdot)\}_{q\geq 1}$  is tight. Then, one can extract a subsequence which converges weakly to an invariant measure (see e.g. Meyn-Tweedie (1992)).

(ii) Uniqueness of Invariant Measure. It is sufficient to claim

$$\mathbb{E}(Y_{k\delta}^{x,i} - Y_{k\delta}^{x,i}|^p) \le c \mathrm{e}^{-\rho k\delta} |x - y|^p.$$
(12)

Remark:

- (11) and (12) can be obtained by using the Perron-Frobenius Theorem plus Proposition 4.2 (Bardet et al. (2010)).
- Actually, a upper bound of  $\delta \in (0,1)$  such that Theorem 2 holds can be given as follows

$$\delta < (1/(16L^2)) \wedge (\eta_p/\alpha)^{2/p}.$$

•  $(\overline{Y}_{k\delta}^{x,i}, \Lambda_{k\delta}^i)$ , associated with Example I, admits a unique invariant measure  $\pi^{\delta} \in \mathcal{P}(\mathbb{R} \times \mathbb{S})$  whenever the stepsize is sufficiently small. Jianhai Bao (CSU) Approximation of Invariant Measures for Regional Aug., 2014 15/32 (Theorem 3) Under conditions of Theorem 2, for sufficiently small  $\delta \in (0,1)$ ,

$$W_p(\mu,\mu^{\delta}) \le c\delta^{p/2}, \quad p \in (0,1 \land p_0),$$

where

$$W_p(\mu,\nu) := \inf_{\pi \in \mathcal{C}(\mu,\nu)} \int_{\mathbb{R}^n \times \mathbb{S}} \int_{\mathbb{R}^n \times \mathbb{S}} d(x,y)^p \pi(\mathrm{d} x, \mathrm{d} y), \quad p \in (0,1],$$

(Theorem 4) Let  $N < \infty$ , (10), (H), and (7) hold. Assume further that

$$\min_{i\in\mathbb{S}}\{-q_{ii}/\beta_i,\beta_i>0\}>1.$$
(13)

Then  $(\overline{Y}_{k\delta}^{x,i}, \Lambda_{k\delta}^i)$  has a unique invariant measure  $\pi^{\delta} \in \mathcal{P}(\mathbb{R}^n \times \mathbb{S})$  whenever the stepsize  $\delta \in (0,1)$  is sufficiently small.

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#### Example II

Let  $\{\Lambda_t\}_{t\geq 0}$  be a right-continuous Markov chain taking values in  $\mathbb{S}$  :=  $\{0, 1, 2\}$  with the generator

$$Q = \begin{pmatrix} -(3+\nu) & \nu & 3\\ 1 & -3 & 2\\ 1 & 2 & -3 \end{pmatrix}$$

for some  $\nu \ge 0$ . Consider a scalar linear SDE with regime switching

$$dX_t = \alpha_{\Lambda_t} X_t dt + \sigma_{\Lambda_t} X_t dW_t, \quad t \ge 0, \quad X_0 = x, \ \Lambda_0 = i_0, \tag{14}$$

where  $\alpha_{\cdot}, \sigma_{\cdot} : \mathbb{S} \mapsto \mathbb{R}$  such that

$$\alpha_0 = \frac{1}{2}, \alpha_1 = -2, \alpha_2 = -3, \quad \sigma_0 = \frac{1}{3}, \sigma_1 = 2, \sigma_2 = 1.$$

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Observe that (10) holds with L = 4, and (**H**) holds for  $\beta_0 = \frac{10}{9}, \beta_1 = 0$ , and  $\beta_2 = -5$ . Since the Markov chain possesses the stationary distribution

$$\mu = (\mu_0, \mu_1, \mu_2) = \left(\frac{5}{20 + 5\nu}, \frac{6 + 3\nu}{20 + 5\nu}, \frac{9 + 2\nu}{20 + 5\nu}\right),$$

it is easy to see that (7) and (13) are satisfied respectively for any  $\nu \geq 0$ . Then,  $(\overline{Y}_{k\delta}^{x,i}, \Lambda_{k\delta}^i)$  has a unique invariant measure for sufficiently small  $\delta \in (0, 1)$ .

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#### Numerical Invariant Measure: Reversible Case

In this section, we assume that the Markov chain  $\{\Lambda_t\}_{t\geq 0}$  is reversible, i.e.,  $\pi_i q_{ij} = \pi_j q_{ji}, i, j \in \mathbb{S}$ , for some probability measure  $\pi := (\pi_1, \cdots, \pi_N)$ . To begin with, we need to introduce some notation. Let

$$L^{2}(\pi) := \Big\{ f \in \mathscr{B}(\mathbb{S}) : \sum_{i=1}^{N} \pi_{i} f_{i}^{2} < \infty \Big\}.$$

Then  $(L^2(\pi), \langle \cdot, \cdot \rangle_0, \|\cdot\|_0)$  is a Hilbert space. Define the bilinear form  $(D(f), \mathscr{D}(D))$  as

$$D(f) := \frac{1}{2} \sum_{i,j=1}^{N} \pi_i q_{ij} (f_j - f_i)^2 - \sum_{i=1}^{N} \pi_i \beta_i f_i^2, \quad f \in L^2(\pi),$$

where  $\beta_i \in \mathbb{R}, i \in \mathbb{S}$ , is given in (H), and the domain

$$\mathscr{D}(D) := \{f \in L^2(\pi) : D(f) < \infty\}_{\text{for a set of } \mathbb{R}}$$

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The principal eigenvalue  $\lambda_0$  of D(f) is defined by

$$\lambda_0 := \inf \{ D(f) : f \in \mathscr{D}(D), \|f\|_0 = 1 \}.$$

For more details on the first eigenvalue, refer to Chen (2000, 2005) . Due to the fact that the state space of  $\{\Lambda_t\}_{t\geq 0}$  is finite, there exists  $\xi = (\xi_1, \cdots, \xi_N) \in \mathscr{D}(D)$  such that

$$D(\xi) = \lambda_0 \|\xi\|_0^2.$$
 (15)

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Define the operator

$$\Omega := Q + \operatorname{diag}(\beta_1, \cdots, \beta_N),$$

where Q is the Q-matrix of  $\{\Lambda_t\}_{t\geq 0}$ , and  $\beta_i \in \mathbb{R}$  such that (**H**).

(Theorem 5) Let  $N < \infty$ , (10) and (H) hold, and assume further  $\lambda_0 > 0$ . Then,  $(\overline{Y}_{k\delta}^{x,i}, \Lambda_{k\delta}^i)$  admits a unique measure  $\pi^{\delta} \in \mathcal{P}(\mathbb{R}^n \times \mathbb{S})$  whenever the stepsize  $\delta \in (0, 1)$  is sufficiently small. Proof: Recalling (15) and checking the argument of Theorem 3.2] (Shao-Xi,

2014), one has

$$\xi \gg \mathbf{0}$$
 and  $(Q\xi)(i) + \beta_i \xi_i = -\lambda_0 \xi_i, \ i \in \mathbb{S}.$ 

Then, the desired assertion follows by following an argument of Theorem 2.

#### Example IV

Let  $\{\Lambda_t\}_{t\geq 0}$  be a right-continuous Markov chain taking values in  $\mathbb{S}$  :=  $\{0, 1, 2\}$  with the generator

$$Q = \begin{pmatrix} -b & b & 0\\ 2a & -2(a+b) & 2b\\ 0 & 3a & -3a \end{pmatrix}$$

for some a, b > 0. Consider a scalar SDE with regime switching

$$dX_t = \alpha_{\Lambda_t} X_t dt + \sigma_{\Lambda_t} X_t dW_t, \quad t \ge 0, \quad X_0 = x,$$
(16)

where  $\alpha_{\cdot}, \sigma_{\cdot} : \mathbb{S} \mapsto \mathbb{R}$  such that

$$c_0 = 2\alpha_0 + \sigma_0^2 < 0, \quad c_1 = 2\alpha_1 + \sigma_1^2, \quad c_2 = 2\alpha_2 + \sigma_2^2.$$

We further assume that

$$b + c_0 < 0, \quad a - b - c_1 > 0, \quad a - c_2 > 0.$$
 (17)

Note that (10) holds with  $L = \max_{i \in \mathbb{S}} \{ |\alpha_i| + |\sigma_i| \}$  and (H) holds with

$$\beta_0 = c_0, \ \beta_1 = c_1, \ , \beta_2 = c_2.$$

Moreover, by the notion of  $\Omega$ , for  $\xi_i = i + 1$ , i = 0, 1, 2, we deduce that

$$(\Omega\xi)(0) = -(-b-c_0)\xi_0, \quad (\Omega\xi)(1) = -(a-b-c_1)\xi_1, \quad (\Omega\xi)(2) = -(a-c_2)\xi_0,$$

Taking

$$\lambda = \min\{-b - c_0, a - b - c_1, a - c_2\} > 0$$

thanks to (17), one finds that

$$(\Omega\xi)(i) \le -\lambda\xi_i, \quad i = 0, 1, 2.$$

Then  $\lambda_0 > 0$  due to Theorem 4.4 (Shao-Xi, 2014, see also Chen, 2000). As a result,  $(\overline{Y}_{k\delta}^{x,i}, \Lambda_{k\delta}^i)$  has a unique invariant measure whenever the stepsize is sufficiently small.

Remark: Theorem 5 can also be extended into the case of RSDPs with a finite state space (i.e.  $N = \infty$ ) provided that  $\lambda_0$  is attainable, i.e., there exists  $f \in L^2(\pi), f \neq 0$ , such that  $D(f) = \lambda_0 ||f||_0^2$ .

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We further suppose that

$$K := \sup_{i \in \mathbb{S}} \beta_i < \infty \quad \text{and} \quad \sup_{i \in \mathbb{S}} (-q_{ii}) < \infty,$$
(18)

where  $\beta_i \in \mathbb{R}$  is given in (**H**). Let us insert m points in the interval  $(-\infty, K]$  as follows:

$$-\infty =: k_0 < k_1 < \dots < k_m < k_{m+1} := K.$$

Then, the interval  $(-\infty, K]$  is divided into m + 1 sub-intervals  $(k_{i-1}, k_i]$ indexed by *i*. Let

$$F_i := \{ j \in \mathbb{S} : \beta_j \in (k_{i-1}, k_i] \}, \quad i = 1, \cdots, m+1.$$

Without loss of generality, we can and do assume that each  $E_i$  is not empty.Jianhai Bao (CSU)Approximation of Invariant Measures for RegiAug., 201425 / 32

# Numerical Invariant Measure: Countable State Space (Cont.)

#### Then

$$F:=\{F_1,\cdots,F_{m+1}\}$$

is a finite partition of  $\mathbb S.$  For  $i,j=1,\cdots,m+1,$  set

$$q_{ij}^F := \begin{cases} \sup_{r \in F_i} \sum_{k \in F_j} q_{rk}, & j < i, \\ \inf_{r \in F_i} \sum_{k \in F_j} q_{rk}, & j > i, \\ -\sum_{j \neq i} q_{ij}^F, & i = j. \end{cases}$$

So  $Q^F := (q_{ij}^F)$  is the Q-matrix for some Markov chain with the state space  $\mathbb{S}_0 := \{1, \cdots, m+1\}.$ 

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For 
$$i = 1, \dots, m + 1$$
, let  

$$\beta_i^F := \sup_{j \in F_i} \beta_j, \qquad H_{m+1} := \begin{pmatrix} 1 & 1 & 1 & \dots & 1 \\ 0 & 1 & 1 & \dots & 1 \\ \vdots & \vdots & \vdots & \dots & \vdots \\ 0 & 0 & 0 & \dots & 1 \end{pmatrix}_{(m+1) \times (m+1)}$$

(**Theorem 5**) Let  $N = \infty$ , (10), (**H**) and (18) hold. Assume further that  $\{\Lambda_t\}_{t\geq 0}$  is ergodic and that

$$-(Q^F + \operatorname{diag}(\beta_1^F, \cdots, \beta_{m+1}^F))H_{m+1}$$

is a nonsingular M-matrix. Then  $(\overline{Y}_{k\delta}^{x,i}, \Lambda_{k\delta}^i)$  admits an invariant measure  $\pi^{\delta} \in \mathcal{P}(\mathbb{R}^n \times \mathbb{S})$  whenever the stepsize  $\delta \in (0,1)$  is sufficiently small. Jianhai Bao (CSU) Approximation of Invariant Measures for Regi Aug. 2014 27/32 In this talk, we are concerned with long-time behavior for EM schemes associated with a range of regime-switching diffusion processes. In particular, existence and uniqueness of numerical invariant measures are addressed

- (i) For regime-switching diffusion processes with finite state spaces by the Perron-Frobenius theorem if the "averaging condition" holds,
- And, with regard to reversible Markov chain, via the principal eigenvalue approach provided that the principal eigenvalue is positive;
- (ii) For regime-switching diffusion processes with countable state spaces by a finite partition method and an M-Matrix theory.
- Also, we reveal that numerical invariant measures converge in the Wasserstein metric to the underlying ones.

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#### Thanks A Lot !

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