

9th Workshop on Markov Processes and Related Topics

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# The Motion of a Tagged Particle in the Simple Exclusion Process

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## Joint work with Peng Chen

1. The model and basic results
2. new results and some questions

The exclusion process is an **interacting particle system**.

Underlying space  $S$ , usually is the set of vertices of a graph  $(V, E)$ .

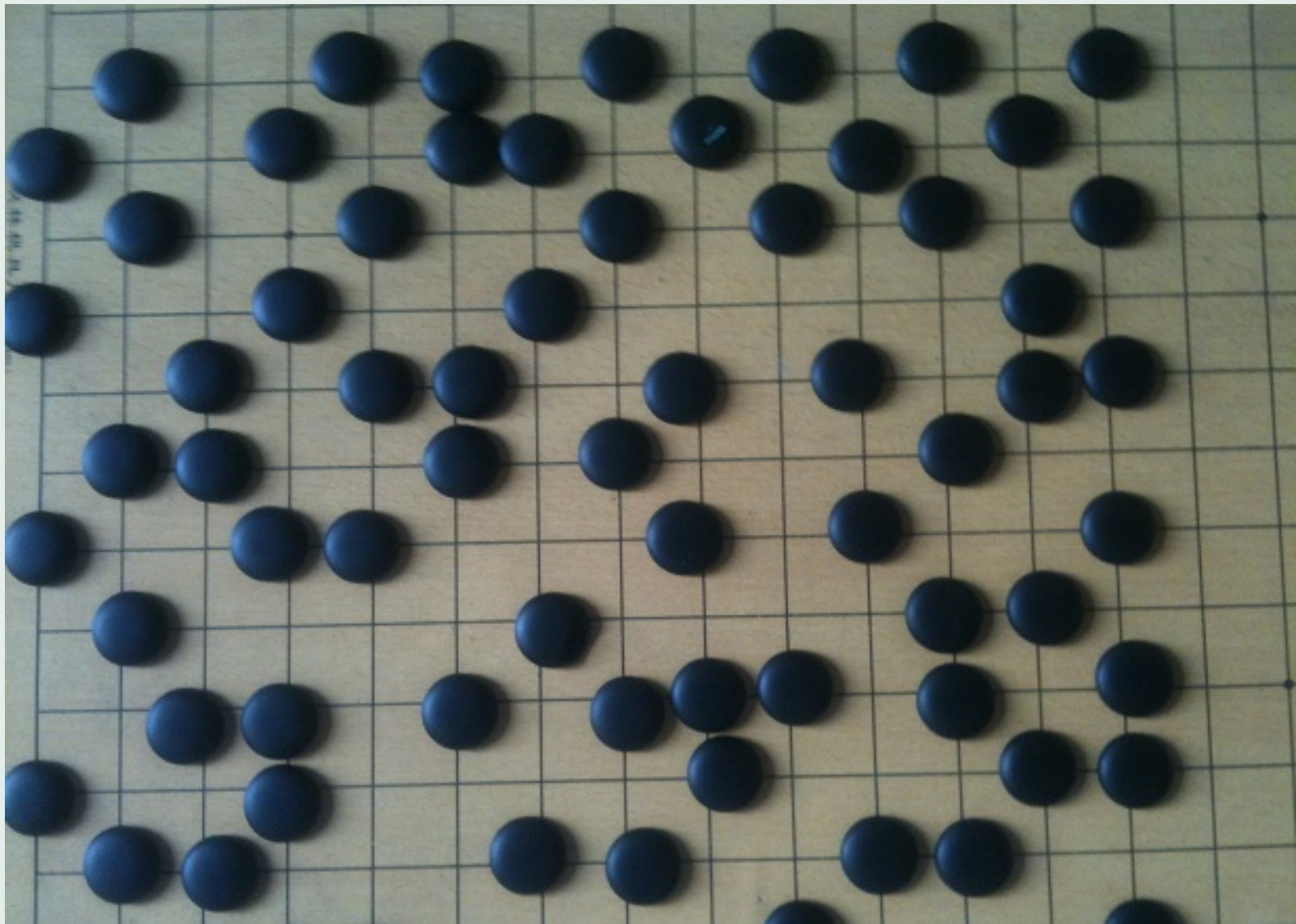
The default choice is the lattice  $\mathbb{Z}^d$

A **configuration**  $\eta$  is a point of  $\{0, 1\}^S$ .

$$\eta = \{\eta(x); x \in S\}.$$

There is a particle at  $x$  if  $\eta(x) = 1$

and site  $x$  is unoccupied if  $\eta(x)=0$ .



Transition mechanisms of particles.

1. at most one particle in every site of  $S$ .
2. A particle at  $x$  **waits** for an exponential time and **attempts** to jump to another site  $y$  with probability  $p(x, y)$ .
3. If  $y$  is vacant, particle moves to  $y$ ; if  $y$  is occupied, then particle stays in  $x$  and the attempt is suspended.

$p(x, y)$  is the transition probability of a Markov chain on  $S$ .

Extra assumptions on  $p(x, y)$  are made usually.

E.g.  $p(x, y) = 1/d_x$  if  $|x - y| = 1$  and  $p(x, y) = 0$  if  $|x - y| \neq 1$ .

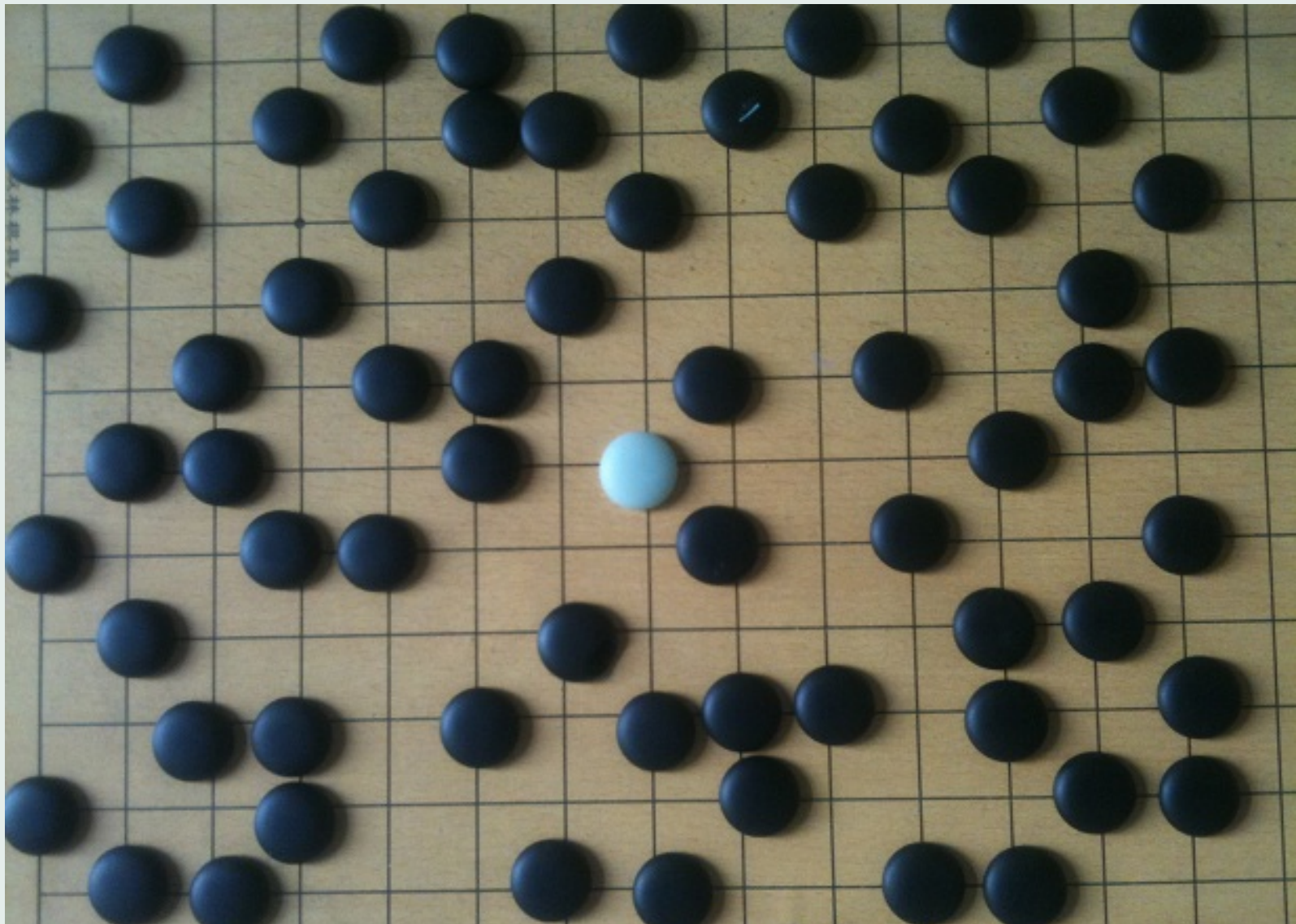
No birth and death, the density of particles is preserved.

The Bernoulli product measure  $\mu_\rho$  is invariant (and **ergodic**).

No easy to identify all invariant measures. *symmetric or  $Z^1$  nearest neighbor,*  
*or  $Z^1$  mean zero.*

Assume that the initial measure is the Bernoulli product measure  $\mu_\rho$ .

*(although the conclusions could be valid in a more general setting.)*



Mark a particle (called the tagged particle).

**Goal:** to study the motion  $X(t)$  of the tagged particle.

$X(t)$  behaves very much like a random walk on  $S$ ,  
except some suspensions due to collision with other particles.

If the initial measure is the Bernoulli product measure  $\mu_\rho$ ,  
an attempt to jump will be suspended with probability  $\rho$ .

It is **reasonable** to expect that

$$\lim_{t \rightarrow \infty} \frac{X(t)}{t} = (1 - \rho) \sum_y y p(0, y) \quad a.s.$$



## Basic Results

1. LLN

2. CLT

3. Invariance principle

$$\lim_{t \rightarrow \infty} \frac{X(t)}{t} = (1 - \rho) \sum_y y p(0, y) \quad a.s.$$

Verified in two cases:

- 1)  $S = Z^1$  and  $p(x, x + 1) = 1$  (totally asymmetric).
- 2)  $S = Z^1$  and  $p(x, x + 1) = p(x, x - 1) = 1/2$

However, it is not trivial at all. In the second case above

$$EX_t^2 \approx c\sqrt{t}.$$

$X(t)$  is **NOT** a random walk with a certain rate of suspension. It is **subdiffusive**.

**Key step:** to verify that the environment viewed from the tagged particle is stationary and **ergodic**.

Ergodicity of  $\mu_\rho$  can not be inherited automatically when  $\mu_\rho$  is conditioned on  $\eta(0) = 1$ .

Assuming translational invariance  $p(x, y) = p(0, y - x)$  for all  $x, y$ , this was done by E. Saada in the following cases:

- 1)  $\mathbb{Z}^d, d \geq 2$ ,
- 2)  $\mathbb{Z}^1, p(x, x + 1) + p(x, x - 1) < 1$ .

and by P.A. Ferrari

- 3)  $\mathbb{Z}^1, p(x, x + 1) + p(x, x - 1) = 1$ .

CLT (Kipnis 85, Kipnis & Varadhan 85).

$$Z_t = \frac{X_t - EX_t}{\sqrt{t}}$$

is asymptotically normal if

- 1)  $S = Z^1$ ,  $p(x, x + 1) + p(x, x - 1) = 1$ ; or
- 2)  $S = Z^d$ ,  $p(x, y) = p(y, x) = p(0, y - x)$ , irreducibility of the random walk and  $\sum_x |x|^2 p(0, x) < \infty$ .

But both excludes the case that  $S = Z^1$ ,  $p(x, x + 1) = p(x, x - 1) = 1/2$ .

- 3)  $S = Z^d$ ,  $\sum_y yp(0, y) = 0$ . (Varadhan 1995)

- 4)  $S = Z^d$ ,  $d \geq 3$ ,  $\sum_y yp(0, y) \neq 0$ . (Sethuraman, Varadhan and Yau 1999)

**Theorem** (Arratia 83): If  $S = Z^1$ ,  $p(x, x + 1) = p(x, x - 1) = 1/2$  and the initial distribution is the Bernoulli product measure  $\mu_\rho$  conditioned on  $\eta(0) = 1$ .  $X(t)$  is the position of the tagged particle initially at the origin. Then  $X_t/t^{1/4}$  converges in distribution to the normal law with mean zero and variance  $\sqrt{2/\pi}(1 - \rho)/\rho$ . Furthermore

$$\lim_t \frac{\text{var}(X_t)}{\sqrt{t}} = \sqrt{\frac{2}{\pi}} \frac{1 - \rho}{\rho}.$$

**Invariance Principle:** As  $N \rightarrow \infty$ ,  $Z_t^N = Z_{Nt}$  converges to a Brownian motion with a non-degenerated coefficient.

the exceptional case

Let  $\sigma_X^2 = \sqrt{2/\pi}(1 - \rho)/\rho$ .

$$\frac{X(\lambda t)}{\sigma_X \lambda^{1/4}} \Rightarrow B_{1/4}(t),$$

where  $B_{1/4}(t)$  is the standard fractional Brownian motion with parameter 1/4. M. Peligrad, S. Sethuraman. *On fractional Brownian motion limits in one dimensional nearest-neighbor symmetric simple exclusion*. ALEA. 4 (2008), 245–255.

## Some new results

1. random environments
2. with a stirring
3. on a regular tree.



I: random environment (RWRE, slow down)

$S = \mathbb{Z}^1$ ,  $\{\omega_i, i \in \mathbb{Z}^1\}$  are i.i.d. random variables,  $0 < c < \omega < c^{-1}$ . Fix the environment, then run an exclusion process.

A particle at site  $i$  attempts to jump to  $i + 1$  at rate  $\omega_i$  and attempts to jump to  $i - 1$  at rate  $\omega_{i-1}$ .

A particle at site  $i$  waits for an exponential time with parameter  $\omega_{i-1} + \omega_i$ . When the clock rings the particle attempts to jump with transition probability

$$p(i, i + 1) = \frac{\omega_i}{\omega_{i-1} + \omega_i}, \quad p(i, i - 1) = \frac{\omega_{i-1}}{\omega_{i-1} + \omega_i}.$$

$X_t$  = position of a tagged particle at time  $t$ .  $X_0 = 0$ .

Particles are assigned to sites other than the origin independently with probability  $\rho$ .

**Theorem** (Jara and Landim (2008)). For almost all environment  $\omega$ ,

$$\frac{X(t)}{t^{1/4}} \Longrightarrow Y, \quad \text{and} \quad Y \sim N\left(0, \frac{2(1-\rho)}{\rho\sqrt{\alpha\pi}}\right)$$

where  $\alpha = E\omega_i^{-1}$ .

**Remark:** When  $\omega_i = 1/2$ , this is reduced to the result of Arratia.

If  $E\omega_i = 1/2$ , then  $\alpha = E\omega_i^{-1} \geq 2$  and

$$\sqrt{\frac{2(1-\rho)}{\pi\rho}} \geq \frac{2(1-\rho)}{\sqrt{\alpha\pi}\rho}.$$

Randomness indeed **slows down** the motion of the tagged particle.

A different approach is to estimate

$$J(t) = J(t)^+ - J(t)^-$$

the net left-to-right particle current across the origin up to time  $t$ .

$X(t)$  can be approximated by  $J(t)/\rho$ .

Theorem (P. Chen). For almost all environment  $\omega$ ,

$$\frac{J(t)}{t^{1/4}} \Longrightarrow Z, \quad \text{and} \quad Z \sim N\left(0, \frac{2(1-\rho)\rho}{\sqrt{\alpha\pi}}\right)$$

where  $\alpha = E\omega_i^{-1}$ .

II, “Stirring-Exclusion” process on  $\mathbb{Z}^d$ . De Masi, Ferrari, Goldstein, & Wick (1989)

P. Chen & F. Zhang: Limit theorems for the position of a tagged particle in the stirring-exclusion process, *Frontiers of Mathematics in China*, Vol.8, No.3, 479-496, 2013

$p(x, y)$  and  $p_{st}(x, y)$ : the probability transition functions for two discrete time Markov chains on  $\mathbb{Z}^d$ .

Intuitive description:

Associate each ordered pair  $(x, y)$  in  $\mathbb{Z}^d$  with a rate  $p(x, y)$  Poisson process, denoted by  $\mathcal{N}^{x,y}$ .

Associate each unordered pair  $\{x, y\}$  in  $\mathbb{Z}^d$  with a rate  $rp_{st}(x, y)$  Poisson process, for some constant  $r$ , denoted by  $\mathcal{N}\{x,y\}$ .

All these Poisson processes are mutually independent.

“**exclusion dynamics**”. At each event time of  $\mathcal{N}^{x,y}$ , the particle at the site  $x$ , if there’s any, jumps to the site  $y$  if in addition  $y$  is empty; otherwise, nothing happens.

“**stirring dynamics**” . At each event time of  $\mathcal{N}^{\{x,y\}}$ , if  $x$  and  $y$  are both occupied, then interchange the positions of the particles at sites  $x$  and  $y$ ; otherwise, nothing happens.

Assumption A:

$p(x, y)$  **irreducible**, translational-invariant, finite range,  $p(0, 0) = 0$ .

Not the nearest-neighbor case in one dimension.

$p_{st}(x, y)$  **symmetric**, translational-invariant, finite range,  $p_{st}(0, 0) =$

0.

**Theorem** (LLN & CLT): Fix any constant  $\rho \in [0, 1]$ . Under Assumption A and the measure  $\mathbb{P}_{\nu_\rho^*}$ , then

$$\lim_{t \rightarrow \infty} \frac{\mathbf{X}_t}{t} = (1 - \rho)m \quad a.s.$$

When  $m \neq 0$ ,  $\mathbf{X}_t/t^{1/2}$  converges in distribution, as  $t \uparrow \infty$ , to a mean zero Gaussian random vector with covariance matrix denoted by  $D(\rho)$ .

III: Simple exclusion process on tree.

$T_d$  = regular tree of degree  $d + 1$ .

Consider the simple random walk on  $T_d$ .

Fix a site as the **root** and the walker is at the root initially.

A walker **waits** for an exponential time with parameter 1, and **moves** to a neighboring site with probability  $1/(d + 1)$  when the clock rings.

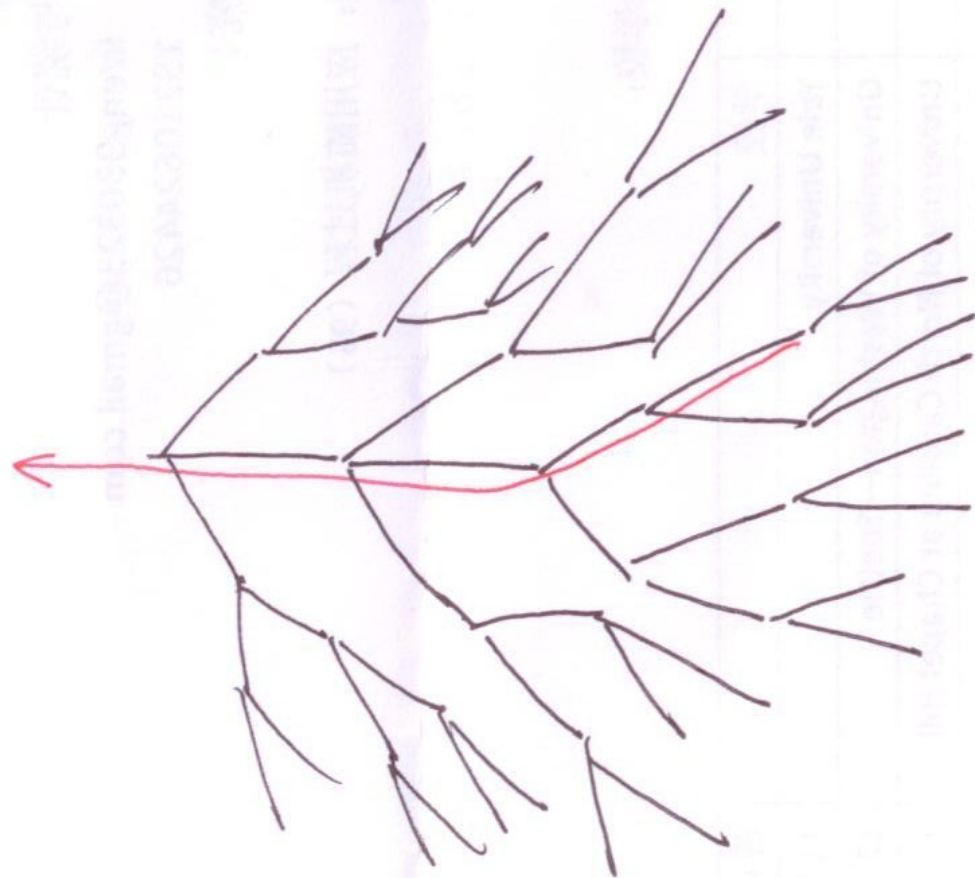
$Y(t)$  = distance between the walker and the root at time  $t$ .

Fix a ray from the root to infinity  $\gamma$ .

At each jump, the walker moves towards the infinity or away from the infinity along the ray  $\gamma$  by one unit.



a ray to  
infinity



Let  $\xi_k$  be i.i.d. random variables with

$$P(\xi = 1) = \frac{d}{d+1}, \quad P(\xi = -1) = \frac{1}{d+1}.$$

$\{K(t); t \geq 0\}$  be a Poisson process with parameter 1.

$$Z_t = \sum_{k=1}^{K(t)} \xi_k.$$

Then  $\lim_t (Z(t) - Y(t))$  exists and

$$\lim_{t \rightarrow \infty} \frac{Y(t)}{t} = \lim_{t \rightarrow \infty} \frac{Z(t)}{t} = \frac{d-1}{d+1}.$$

## The simple exclusion process on tree.

Each particle performs a random walk, with any possible collision being suspended.

The initial distribution is the Bernoulli product measure  $\mu_\rho$ .

$\mu_\rho$  is invariant.

Suppose there is a particle at the root initially.

$X(t)$  = distance between the tagged particle and the root at time  $t$ .

Then we expect

$$\lim_{t \rightarrow \infty} \frac{X(t)}{t} = \lim_{t \rightarrow \infty} (1 - \rho) \frac{Y(t)}{t} = (1 - \rho) \frac{d - 1}{d + 1}.$$

The environment, viewed from the tagged particle, is **stationary** and **ergodic**.

Let  $\mu_\rho$  = the Bernoulli product measure,

and  $\mu_\rho^* = \mu_\rho\{\cdot | \eta(0) = 1\}$ .

$X(t)$  = the position of the tagged particle at time  $t$ .

$\xi_t(x) = \eta_t(X(t) + x)$ .

**Theorem:**  $\mu_\rho^*$  is **stationary** and **ergodic** of the process of  $\xi_t$ .

The proof of ergodicity follows essentially from the idea of Saada.

Consecutive jumps of the tagged particle

$$\xi_1, \xi_2, \xi_3, \dots, \xi_n \dots,$$

are **stationary** and **ergodic**

and the position of the tagged particle

$$X_t = \xi_1 + \xi_2 + \xi_3 \dots + \xi_n.$$

However we are unable to draw the conclusion of the speed  $X(t)/t$  because the tree is a non-Abelian group,  $\xi_1 + \xi_2 \neq \xi_2 + \xi_1$ .

$$\lim_t \frac{X(t)}{t} = (1 - \rho) \frac{d - 1}{d + 1} ?$$

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# Thank You

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