On time regularity of generalized Ornstein-Uhlenbeck processes with cylindrical stable noise

Yong LIU, Jianliang ZHAI

School of Mathematical Sciences, Peking University

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## Outline

- Problems
- Main Results
- Proofs
- Some Discussions



Problems Main Results Proofs Some Discussions

访问主页

标题页

第 <mark>2</mark> 页 共 28 页

返回

全屏显示

关闭

退出

••

▶

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## **1** Problems

$$dX(t) = AX(t)dt + dL(t), \ t \ge 0.$$
(1)

- *H*, a separable Hilbert space ,  $\langle \cdot, \cdot \rangle_H$ .
- A, generator of a  $C_0$ -semigroup on H,  $A^*$  the adjoint operator of A.
- L, Lévy process,  $L = \sum_{n=1}^{\infty} \beta_n L^n(t) e_n$ ,
- $L^n$ , i.i.d., càdlàg real-valued Lévy processes.
- $\{e_n\}_{n\in\mathbb{N}}$ , fixed reference orthonormal basis in H.
- $\beta_n$ , a sequence of positive numbers.



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标题页

第3页共28页

返回

全屏显示

关 闭

退出

44





## **Problem** :

If the solution of Eq. (1)  $(X(t))_{t\geq 0}$  takes value in H for any t, is there a H-valued càdlàg modification of X? i.e.  $\exists$  ? a H-valued càdlàg  $(\tilde{X}_t)_{t\geq 0}$  such that,

$$\mathbb{P}(X_t = \tilde{X}_t) = 1, \text{ for any } t.$$
(2)



(3)

访问主页		
标 题 页		
44	••	
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 第 <u>5</u> 页 共 <u>28</u> 页		
返	回	
全 屏 显 示		
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Assume that  $\{e_n\}_{n\in\mathbb{N}}\subset \mathscr{D}(A^*)$ , the weak solution of Eq. (1),

 $dX(t) = AX(t)dt + dL(t), \ t \ge 0.$ 

can be represented by for any  $n \in \mathbb{N}$ ,

 $d\langle X(t), e_n \rangle_H = \langle X(t), A^* e_n \rangle_H dt + \beta_n dL^n(t).$ 

 $\langle X(t), e_n \rangle_H \equiv X^n(t).$ 

 $L^n$ ,  $\alpha$ -stable processes,  $\alpha \in (0, 2)$ .

## **1.1.** Property of Sample Paths

#### Kolmogorov's Extension Theorem:

S: State space. construct distribution on  $S^{[0,\infty)}$ .

However, this theorem does not describe the properties of sample paths.

Continuous or càdlàg modification of sample path is a fundamental property in Theory of Stochastic Processes, such as Martingale Theory, Markov Processes and Probabilistic Potential Theory and SDE.

[1] Doob, J.L. *Stochastic Processes*. John Wiley & Sons Inc., New York1953





### **1.2. Generalized Ornstein-Uhlenbeck Processes**

$$dX(t) = AX(t)dt + dL(t).$$

 $L = \sum_{n=1}^{\infty} \beta_n L^n(t) e_n$ ,  $L^n$  i.i.d., càdlàg  $\alpha$ -stable processes.

Modeling some heavy tail phenomenon.

The time regularity of the process X is of prime interest in the study of non-linear Stochastic PDEs.

And these studies of generalized O-U processes is a beginning point.





### **1.3.** $l^2$ -valued O-U processes driven by Brownian motion

•  $l^2$ -valued O-U processes driven by Brownian motion

[2] Iscoe, Marcus, McDonald, Talagrand, Zinn, (1990) Ann. Proba.

 $dx_k(t) = -\lambda_k x_k(t) dt + \sqrt{2a_k} dB_k, \quad k = 1, 2, \cdots.$ 

They gave a simple but quite sharp criterion for continuity of  $X_t$  in  $l^2$ . **Theorem 1 in [2]** f(x) positive function on  $[0, \infty)$  such that  $\frac{f(x)}{x}$  nondecreasing for  $x \ge x_1 > 0$  and

$$\int_{x_1}^{\infty} \frac{dx}{f(x)} < \infty, \quad \sum_k \frac{a_k}{\lambda_k} < \infty, \quad \sup_k \frac{f(a_k) \vee x_1}{\lambda_k \vee 1} < \infty.$$
(4)

Then,  $x_t$  is continuous in  $l^2$  a.s. Moreover, this result is best possible in the sense that it is false for any function f(x), which satisfies all the above hypotheses with the exception that  $\int_{x_1}^{\infty} \frac{dx}{f(x)} = \infty$ .

• *H* or *B*-valued O-U processes

[3] Millet, Smolenski (1992) Prob. Theory Related Fields.





#### 1.3.1. O-U Eq. with Lévy noise

- [4] Fuhrman, Röckner (2000) Generalized Mahler semigroups: the non Gaussian case, Potential Anal., 12(2000), 1-47.
  - There is an enlarged space E,  $H \subset_{HS} E$ , such that  $(X(t))_{t\geq 0}$  has a càdlàg path in E.
- [5] Priola, E., Zabczyk, J. On linear evolution with cylindrical Lévy noise, in: SPDE and Applications VIII, Proceedings of the Levico 2008 Conference.
  - L(t) symmetric, and  $L(t) \in U \supset H$ , they give a necessary and sufficient condition of  $X_t \in H$ , for any t > 0.
- [6] Brzeźniak, Z., Zabczyk, J. *Regularity of Ornstein-Uhlenbeck processes driven by Lévy white noise*, Potential Anal. 32(2010)153-188.
  - L(t), Lévy white noise obtained by subordination of a Gaussian white noise.  $L_t = W(Z(t))$ , Spatial continuity, Time irregularity.





- Problems Main Results Proofs Some Discussions



 [7] Priola, E., Zabczyk, J. Structural properties of semilinear SPDEs driven by cylindrical stable process, Probab. Theory Related Fields, 149(2011), 97-137 [PZ11]

• They conjectured in Section 4 in [7], If  $L^n$  are symmetric  $\alpha$ -stable processes,  $\alpha \in (0,2)$ , the H-càdlàg property of Eq. (1) holds under much weaker conditions than  $\sum_{n=1}^{\infty} \beta_n^{\alpha} < \infty$ .

**Remark 1.**  $\sum_{n=1}^{\infty} \beta_n^{\alpha} < \infty \Leftrightarrow L(t) = \sum_{n=0}^{\infty} \beta_n L^n(t) e_n$  has *H*-càdlàg property.

**Remark 2.** In general,  $L \in H \Rightarrow X$  has *H*-càdlàg path.

[8] Brzeźniak, Z., Goldys, B., Imkeller, P., Peszat, S., Priola, E., Zabczyk, J. *Time irregularity of generalized Ornstein-Uhlenbeck processes*, C. R. Acad. Sci. Paris, Ser. I 348(2010), 273-276. [BGIPPZ10]

 $dX(t) = AX(t)dt + dL(t), \ t \ge 0.$ 

$$d\langle X(t), e_n \rangle_H = \langle X(t), A^* e_n \rangle_H dt + \beta_n dL^n(t), \ n \in \mathbb{N}.$$

$$\langle X(t), e_n \rangle_H \equiv X^n(t).$$
(5)

• Theorem 2.1 [8] X, *H*-valued process,  $(e_n) \in \mathscr{D}(A^*)$ ,  $\beta_n \not\rightarrow 0$ , then X has no *H*-càdlàg modification with probability 1.

• Question 1,2,3,4 ... ...







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标题页

第 12 页 共 28 页

返回

全屏显示

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退出

44

- [9] Brzeźniak, Z., Otobe, Y. and Xie B. Regularity for SPDE driven by  $\alpha$ -stable cylindrical noise. 2011, preprint
  - They obtained detailed results of spatial regularity and temporal integrability.

## **2** Main Results

 $L = \sum_{n=1}^{\infty} \beta_n L^n(t) e_n$ ,  $L^n$  i.i.d. real-valued Lévy processes, Lévy characteristic measure  $\nu$ .  $\{e_n\}_{n \in \mathbb{N}} \subset \mathscr{D}(A^*)$ ,

$$d\langle X(t), e_n \rangle_H = \langle X(t), A^* e_n \rangle_H dt + \beta_n dL^n(t).$$

**Theorem 1** Assume that the process X in Eq. (1) has H-càdlàg modification, then for any  $\epsilon > 0$ ,

$$\sum_{n=1}^{\infty} \nu(|y| \ge \epsilon/\beta_n) < \infty$$

**Remark 3.** This theorem implies Theorem 2.1 in [BGIPPZ10]

 $\beta_n \not\rightarrow 0 \Rightarrow$  no *H*-càdlàg modification





$$L^{n}, \text{ i.i.d. } \alpha \text{-stable process. } \nu(dy) = \begin{cases} c_{1}y^{-1-\alpha}dy, & y > 0, \\ c_{2}|y|^{-1-\alpha}dy, & y < 0. \end{cases}$$

**Theorem 2** Assume  $(L^n, n = 1, 2, \dots)$  are i.i.d., non-trivial  $\alpha$ -stable processes,  $\alpha \in (0, 2)$ , and  $S(t) = e^{At}$  satisfying  $||S(t)||_{L(H,H)} \leq e^{\beta t}$ ,  $\beta \geq 0$ , (generalized contraction principle ), the following three assertions are equivalent:

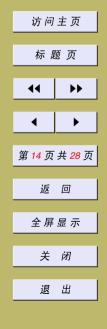
(1) the process  $(X(t), t \ge 0)$  in Eq. (1) has H-càdlàg modification; (2)  $\sum_{n=1}^{\infty} |\beta_n|^{\alpha} < \infty$ ;

(3) the process L is a Lévy process on H.

**Remark 4.** This result denies the conjecture in [PZ11]. And more, Theorem 2 does not need the assumption of symmetry of  $L_n$ .

much weaker than  $\sum_{n=1}^{\infty} |\beta_n|^{\alpha} < \infty$ .







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Remark 5. In [BGIPPZ10],

**Question 3:** Is the requirement of the process L evolves in H also necessary for the existence of H-càdlàg modification of X?

Theorem 2 partly answers Question 3, *i.e.* at least if  $L^n$ , i.i.d.  $\alpha$ -stable processes, L evolving in H is a necessary condition of X having H-càdlàg modification.

Moreover, if A is self-adjoint, eigenvectors  $e_n$ , eigenvalues  $-\lambda_n < 0$ ,  $n \in \mathbb{N}$ ,

$$dX^{n}(t) = -\lambda_{n}X^{n}(t)dt + \beta_{n}dL^{n}(t), \quad t \ge 0, \quad n \in \mathbb{N}.$$
 (6)

For  $\delta \in \mathbb{R}$ ,

$$H_{\delta} \equiv \mathscr{D}(A^{\delta/2}) = \Big\{ x = \sum_{n=1}^{\infty} x_n e_n : \sum_{n=1}^{\infty} \lambda_n^{\delta} |x_n|^2 < \infty, \ x_n \in \mathbb{R} \Big\}.$$

**Proposition 3** Assume  $L^n$  are i.i.d., non-trivial  $\alpha$ -stable processes,  $\alpha \in (0,2)$  and  $X^n$  is the solution of Eq. (6). Then the following assertions are equivalent:

(1) the process  $(X(t), t \ge 0)$  in Eq. (1) has  $H_{\delta}$ -càdlàg modification; (2)  $\sum_{n=1}^{\infty} |\beta_n \lambda_n^{\delta/2}|^{\alpha} < \infty$ ;

(3) the process L is a Lévy process on  $H_{\delta}$ .



Furthermore, we apply Proposition 3 to Stochastic Heat Equation (S.H.E.) on  $\mathcal{O} = (0, \pi)$  with  $\alpha$ -stable noise

$$dX(t) = \Delta X(t)dt + dL(t), \tag{7}$$

**Proposition 4** If  $\beta_n = 1$  for any  $n \in \mathbb{N}$ , Eq. (7) has  $H_{\delta}$ -càdlàg modification if and only if  $\delta < -1/\alpha$ .

#### Remark 6. in [BGIPPZ10]

**Question 4:** Is the process X in S.H.E.  $H_{\delta}$ -càdlàg for  $\delta \in [-\frac{1}{\alpha}, 0)$ ?

Proposition 4 answers Question 4.





**Proposition 5** Assume  $L^n$  are i.i.d., non-trivial symmetric  $\alpha$ -stable processes. If  $(\beta_n, n \ge 1)$  satisfies  $\sum_{n=1}^{\infty} \beta_n^{\alpha}/n^2 < \infty$  and  $\sum_{n=1}^{\infty} \beta_n^{\alpha} = \infty$ , then there is no H-càdlàg modification of  $(X(t), t \ge 0)$  in Eq. (7), even if for any t > 0,  $X(t) \in H$ .

#### Remark 7. In [BGIPPZ10],

**Question 1:** *Does*  $\beta_n \to 0$  *imply existence of a càdlàg modification of X*?

If we set  $\beta_n = n^{-\frac{1}{\alpha}}$ , then  $\sum_{n=1}^{\infty} \beta_n^{\alpha}/n^2 < \infty$ ,  $\sum_{n=1}^{\infty} \beta_n^{\alpha} = \infty$  and  $\beta_n \to 0$  in Eq. (7) (S.H.E.). By Proposition 5, we give an example showing that  $\beta_n \to 0$  does not imply the existence of *H*-càdlàg modification of *X*, even if for any t > 0,  $X(t) \in H$  and the Lévy characteristic measure of *L* supports on *H*. This is a negative answer to Question 1.







**Remark 8.** Question 2 in [BGIPPZ10]: Is  $e_n \in \mathscr{D}(A^*)$  essential for the validity of Theorem 2.1 .

We have no idea to this question.

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第19页共28页
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## **3** Proofs

$$X(t) = \sum_{n=1}^{\infty} X^n(t) e_n, \ X^n(t) = \langle X(t), e_n \rangle_H$$

**Lemma 1** The process  $(X(t), t \ge 0)$  is a H-càdlàg (resp. continuous) process with probability 1, if and only if for any  $n \in \mathbb{N}$ , the process  $(X^n(t), t \ge 0)$  is càdlàg (resp. continuous) process with probability 1 and for any T > 0,

$$\lim_{N \to \infty} \sup_{t \in [0,T]} \sum_{i=N}^{\infty} |X^i(t)|^2 = 0, \quad \text{with probability 1.}$$
(8)





Set riangle f(t) = f(t) - f(t-). Noting that if  $(X(t), t \ge 0)$  is a H-càdlàg process, then

$$\sup_{n \ge N} \sup_{t \in [0,T]} |\Delta X^n(t)| \le 2 \Big( \sup_{t \in [0,T]} \sum_{n=N}^{\infty} |X^n(t)|^2 \Big)^{1/2}$$

**Lemma 2** Assume the process  $(X(t), t \ge 0)$  is a H-càdlàg process with probability 1, then for any T > 0,

 $\lim_{N \to \infty} \sup_{n \ge N} \sup_{t \in [0,T]} |\Delta X^n(t)| = 0, \text{ with probability } 1.$ 





**Proof of Theorem 1** X, H-càdlàg property.

 $\tau_n = \inf\{t > 0 : |\beta_n \Delta L^n(t)| \ge \epsilon\}$ 

 $\tau_n$  independent exponential distributions with parameter  $\psi_n = \nu(|y| \ge \epsilon/\beta_n)$ .

Lemma 2 implies

 $\lim_{N\to\infty} \mathbb{P}\big(\tau_n \leq T, \text{ for some } n \geq N\big) = 0.$ 

$$\mathbb{P}(\tau_n \leq T, \text{ for some } n \geq N) = 1 - \prod_{n \geq N} \mathbb{P}(\tau_n \leq T) = 1 - \exp\left(-\sum_{n=N}^{\infty} \psi_n T\right)$$

$$\sum_{n=1}^{\infty} \nu(|y| \ge \epsilon/\beta_n) = \sum_{n=1}^{\infty} \psi_n < \infty.$$





Applying Theorem 1 to  $\alpha$ -stable processes,

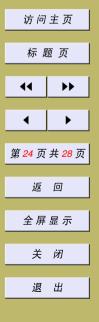
$$\nu(dy) = \begin{cases} c_1 y^{-1-\alpha} dy, & y > 0, \\ c_2 |y|^{-1-\alpha} dy, & y < 0. \end{cases}$$

Theorem 2 holds.

Key point: scaling invariant law of  $\alpha$ -stable law, or power law.



访问主页		
标 题 页		
44	••	
◀		
第 23 页 共 28 页		
返	回	
全屏	显示	
关	闭	
退	出	



## **Proof of Lemma 1**:

 $\Leftarrow \ If$ 

$$\lim_{N \to \infty} \sup_{t \in [0,T]} \sum_{i=N}^{\infty} |X^i(t)|^2 = 0, \quad \text{with probability 1}, \tag{9}$$

then for any  $t \in [0, \infty)$ , for any  $\epsilon > 0$ , by Eq.(9), there exists  $N_{t,\omega,\epsilon} \in \mathbb{N}$ satisfying  $\sup_{s \in [0,t+1]} \sum_{i=N_{t,\omega,\epsilon}}^{\infty} |X^i(s)|^2 \leq \epsilon$ .

$$\limsup_{\substack{s' \downarrow t \\ s' \downarrow t}} \|X(s') - X(t)\|_{H}^{2}$$
(10)  
$$\leq \lim_{s' \downarrow t} \sum_{i=1}^{N_{t,\omega,\epsilon}} |X^{i}(s') - X^{i}(t)|^{2} + 2 \sup_{s \in [0,t+1]} \sum_{i=N_{t,\omega,\epsilon}}^{\infty} |X^{i}(s)|^{2} \leq 2\epsilon.$$
(11)

 $\Rightarrow$  • V is a separable Hilbert space,

K is a compact set in V

 $\Leftrightarrow$ 

K is bounded, closed and,

and for any orthonormal basis  $\{v_n\}_{n\in\mathbb{N}}$  in V, for any  $\epsilon > 0$ , there is a  $N_{\epsilon} \in \mathbb{N}$ 

$$\sup_{x \in K} \sum_{i=N_{\epsilon}}^{\infty} \langle x, v_i \rangle_V^2 < \epsilon.$$

• By the Proposition 1.1 in [10], for any  $x \in D([0,T], H)$ ,

 $\{x(t), t \in [0, T]\} \cup \{x(t-), t \in [0, T]\}$ 

is a compact set in H.

[10] Jakubowski, A. *On the Skorohod topology*, Ann. Inst. Henri Poincaré 22(1986), 263-285.



访问主页		
标题页		
44	••	
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第 25 页 共 28 页		
返	回	
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# **4** Some Discussions

## 4.1. Conclusions

We give a necessary and sufficient condition of càdlàg modification of Ornstein-Uhlenbeck process with cylindrical stable noise in a Hilbert space. By using this condition, we deny a conjecture and answer some questions.

#### 4.2. Further problems

- $X \in B$ , Banach space, ?
- Itô-Stratonovich type SPDE and interacting diffusions driven by stable processes. Time (ir)regularity ? such as Parabolic Andersen Model on  $\mathbb{Z}^d$ .

$$dX_i(t) = \kappa \sum_{j \in \mathbb{Z}^d} a(i, j) X_j(t) dt + X_i(t-) dL_i(t), \quad i \in \mathbb{Z}^d.$$

[11] Furuoya, T., Shiga, T., Sample lyapunov exponent for a class of linear Markovian systems over  $\mathbb{Z}^d$ . Osaka J. Math 35 (1998) 35-72







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第 <mark>28</mark> 页 共 28 页

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