

Decay Property of Markov Branching Processes with Immigration and Disaster

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1 Background

- Definition of Decay parameter

Let \mathbf{E} be a countable set.

$Q = (q_{ij}; i, j \in \mathbf{E})$ be a stable q -matrix.

$(p_{ij}(t); i, j \in \mathbf{E})$ is the Feller minimal Q -process.

C is a communicating class of \mathbf{E} and

$$\lim_{t \rightarrow \infty} p_{ij}(t) = 0, \quad i, j \in C.$$

By Kingman (1936), there exists a number $\lambda_C \geq 0$ such that for all $i, j \in C$,

$$\frac{1}{t} \log p_{ij}(t) \rightarrow -\lambda_C \text{ as } t \rightarrow \infty$$

λ_C is called the decay parameter for C .





On the other hand, let

$$\begin{aligned}\mu_{ij} &= \inf\left\{\lambda \geq 0 : \int_0^{\infty} e^{\lambda t} p_{ij}(t) dt = \infty\right\} \\ &= \sup\left\{\lambda \geq 0 : \int_0^{\infty} e^{\lambda t} p_{ij}(t) dt < \infty\right\}.\end{aligned}$$

It is easily seen that μ_{ij} does not depend on $i, j \in C$, the common value is denoted by μ . Moreover,

$$\lambda_C = \mu.$$

(see, for example, Pollett (2006)).



- Definition of λ_C -recurrence

λ_C -recurrent: $\int_0^\infty e^{\lambda ct} p_{ii}(t) dt = +\infty, \forall i \in C$

λ_C -transient: $\int_0^\infty e^{\lambda ct} p_{ii}(t) dt < +\infty, \forall i \in C$

Positively λ_C -recurrent: $\lim_{t \rightarrow \infty} \int_0^t e^{\lambda ct} p_{ii}(t) dt > 0, \forall i \in C$

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λ_C -subinvariant measure $(m_k; k \in C)$ for Q :

$$\sum_{k \in C} m_k q_{kj} \leq -\lambda_C m_j, m_j > 0 \forall j \in C.$$

It is called λ_C -invariant if the equality holds.

λ_C -subinvariant vector $(x_k; k \in C)$ for Q :

$$\sum_{j \in C} q_{ij} x_j \leq -\lambda_C x_i, x_i > 0, \forall i \in C.$$

It is called λ_C -invariant if the equality holds.

Similarly, one can define λ_C -(sub)invariant measure/vector for $P(t)$.

- **Problems:**

- ▶ $\lambda_C = ?$;

- ▶ The λ_C -recurrency of the process.

- **Known progress:**

- (i) Finite Markov chains.

- (ii) BDP(Chen M.F.).

Special BDP: $q_{i \ i-1} = a$, $q_{i \ i+1} = b$, then $\lambda_C = (\sqrt{a} - \sqrt{b})^2$.

- (iii) MBP: $q_{ij} = ib_{j-i+1}$, then $\lambda_C = -B'(q)$ where

$$B(s) = \sum_{j=0}^{\infty} b_j s^j$$

and q is the smallest nonnegative root of $B(s) = 0$.





(iv) Stopped $M^X/M/1$ queue (Li and Chen, 2008):

$$q_{ij} = \begin{cases} b_{j-i+1}, & \text{if } i \geq 1, j \geq i - 1 \\ 0, & \text{otherwise} \end{cases}$$

$$\lambda_C = \sup\{\lambda \geq 0 : B(s) + \lambda s = 0 \text{ has a root in } (0, +\infty)\}$$

where $B(s) = \sum_{k=0}^{\infty} b_k s^k$.

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(v) Controlled $M^X/M/1$ queue (Li and Chen, 2009):

$$q_{ij} = \begin{cases} h_j, & \text{if } i = 0, j \geq 0 \\ b_{j-i+1}, & \text{if } i \geq 1, j \geq i - 1 \\ 0, & \text{otherwise} \end{cases}$$

λ_C

$= \sup\{\lambda \geq 0 : B(s) + \lambda s \leq 0, \lambda + H(s) \leq 0 \text{ has a root in } (0, 1)\}$

where $B(s) = \sum_{k=0}^{\infty} b_k s^k$ and $H(s) = \sum_{k=0}^{\infty} h_k s^k$.

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- **Description of the models in this talk**

Let $Q = (q_{ij}; i, j \in \mathbf{Z}_+)$ be defined as follows:

$$q_{ij} = \begin{cases} ib_{j-i+1} + a_{j-i}, & \text{if } i \geq 0, j \geq i \\ b_0, & \text{if } i \geq 1, j = (i - 1) \vee 0 \\ 0, & \text{otherwise,} \end{cases} \quad (1)$$

where

$$\begin{cases} b_j \geq 0 (j \neq 1), 0 < \sum_{j \neq 1} b_j \leq -b_1 < \infty \\ a_j \geq 0 (j \neq 0), 0 < \sum_{j=1} a_j \leq a_0 < \infty. \end{cases} \quad (2)$$

Q is called a BI q -matrix.





Definition 1. A Markov branching process with immigration (MBPI) is a continuous Markov chain on the state space \mathbf{Z}_+ whose transition function $P(t) = (p_{ij}(t); i, j \in \mathbf{Z}_+)$ satisfies

$$P'(t) = P(t)Q \quad (3)$$

where Q is a BI q -matrix defined in (1)–(2).

Define

$$A(s) = \sum_{k=0}^{\infty} a_k s^k \quad \text{and} \quad B(s) = \sum_{k=0}^{\infty} b_k s^k. \quad (4)$$



Proposition 1. (i) $A(s) < 0$ for all $s \in [-1, 1)$ and

$$A(s) \uparrow\uparrow A(1) \leq 0 \text{ as } s \uparrow 1.$$

(ii) $B(s)$ is convex on $[0, 1]$ and $B(s) = 0$ possesses a smallest nonnegative root ρ . Moreover, $\rho = 1$ iff $B(1) = 0$ and $B'(1) \leq 0$.

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It is clear that Q is conservative iff $B(1) = A(1) = 0$.

For Q being conservative case:

The recurrence and hitting time properties, Sevast'yanov(1957), Zubkov(1972) and Vatutin(1977).

Li and Chen(2006) considered a more general model in which $q_{0j} = a_j$ ($j \geq 0$) are replaced by arbitrary rates h_j ($j \geq 0$).

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Proposition 2. (Li & Chen 2006) Suppose that $A(1) = B(1) = 0$.

Then

(i) Q is regular iff either $B'(1) < \infty$ or $B'(1) = \infty$ together with $\int_{\varepsilon}^1 \frac{ds}{-B(s)} = \infty$ for some (equivalently for all) $\varepsilon \in (\rho, 1)$ where $\rho < 1$ is the smallest nonnegative root of $B(s) = 0$.

(ii) The MBPI is recurrent iff $B'(1) \leq 0$ and $J = +\infty$ where

$$J := \int_0^1 \frac{1}{B(y)} \cdot e^{\int_0^y \frac{A(x)}{B(x)} dx} dy. \quad (5)$$

Moreover, the MBPI is positive recurrent iff $B'(1) \leq 0$ and

$$\int_0^1 \frac{-A(s)}{B(s)} ds < \infty. \quad (6)$$



If $B(1) < 0$ or $A(1) < 0$, then we can consider another q -matrix $\tilde{Q} = (\tilde{q}_{ij}; i, j \in \mathbf{Z}_+ \cup \{\Delta\})$ (where Δ is an added state):

$$\tilde{q}_{ij} = \begin{cases} 0, & \text{if } i = \Delta, j \in \mathbf{Z}_+ \cup \{\Delta\} \\ -iB(1) - A(1), & \text{if } i \geq 0, j = \Delta \\ ib_{j-i+1} + a_{j-i}, & \text{if } i \geq 0, j \geq i \\ ib_0, & \text{if } i \geq 0, j = i - 1 \\ 0, & \text{otherwise} \end{cases} \quad (7)$$

\tilde{Q} is called a BID q -matrix. The corresponding process is called an MBPID.

This talk is concentrated on the transiency property of Q (or) \tilde{Q} -process.



2 Preliminary

In order to find the exact value of decay parameter λ_Z and discuss the λ_Z -recurrence property, we need some preparation.

Lemma 1. *There always exists only one MBPID which satisfies the Kolmogorov forward equations.*

Lemma 2. *Let Q be defined in (1) – (2) and $P(t) = (p_{ij}(t); i, j \geq 0)$ be the Feller minimal Q -process. Then for any $i \geq 0$ and $|s| < 1$,*

$$\sum_{j=0}^{\infty} p'_{ij}(t) s^j = B(s) \sum_{j=1}^{\infty} p_{ij}(t) j s^{j-1} + A(s) \sum_{j=0}^{\infty} p_{ij}(t) s^j. \quad (8)$$



Lemma 3. Let $P(t) = (p_{ij}(t); i, j \geq 0)$ be a transition function. Then the following two statements are equivalent.

(i) $P(t)$ is the Feller minimal Q -function, where Q takes the form of (1) – (2).

(ii) For any $i \geq 0$, $t \geq 0$, $s \in [-1, 1]$, we have

$$F_i(t, s) = F_0(t, s) \cdot \sum_{j=0}^{\infty} p_{ij}^*(t) s^j \quad (9)$$

where $F_i(t, s) = \sum_{j=0}^{\infty} p_{ij}(t) \cdot s^j$ ($i \geq 0$, $s \in [-1, 1]$) and $P^*(t) = (p_{ij}^*(t); i, j \geq 0)$ is a Markov branching process whose q -matrix Q^* (may not be conservative) is given by

$$q_{ij}^* = \begin{cases} ib_{j-i+1}, & \text{if } i \geq 0, j \geq i - 1 \\ 0, & \text{otherwise} \end{cases} \quad (10)$$

where $\{b_j; j \geq 0\}$ is the same as given in (2).



Sketch of the proof. (i) \Rightarrow (ii). By Lemma 2,

$$\frac{\partial F_i(t, s)}{\partial t} = B(s) \cdot \frac{\partial F_i(t, s)}{\partial s} + A(s)F_i(t, s) \quad (11)$$

where $F_i(t, s) = \sum_{j=0}^{\infty} p_{ij}(t)s^j$. Let Q^* be given by (10) and $P^*(t) = (p_{ij}^*(t); i, j \geq 0)$ be the minimal Q^* -function and define $\hat{P}(t)$ by $\hat{p}_{ij}(t) = \sum_{k=0}^j p_{0k}(t)p_{kj}^*(t)$. Then $\hat{P}'(t) = \hat{P}(t)Q$. By Lemma 1, we must have $\hat{P}(t) = P(t)$.

(ii) \Rightarrow (i). Note that for any $i, j \geq 0$ and $0 < s < 1$,

$$p_{ij}(t)s^j \leq F_0(t, s) \left(\sum_{k=0}^{\infty} p_{1k}^*(t)s^k \right)^i.$$

which leads $\lim_{i \rightarrow \infty} p_{ij}(t) = 0$. Therefore, by Reuter and Riley [7] or Anderson [1], $P(t)$ is the Feller minimal Q -function. \square





3 Conclusions

Theorem 1. *Let Q be defined as in (1) – (2) and $P(t) = (p_{ij}(t); i, j \geq 0)$ be the Feller minimal Q -function. Then*

$$\lambda_Z = -A(\rho)$$

where ρ is the smallest nonnegative root of $B(s) = 0$. In particular, $\lambda_Z = 0$ if and only if $\rho = 1$ and $A(1) = 0$, i.e., if and only if Q is conservative and $B'(1) \leq 0$.

Sketch of the proof.

(i) $\lambda_Z \geq -A(\rho)$. $(\rho^k; k \geq 0)$ is a $-A(\rho)$ -invariant vector for Q .

(ii) $\lambda_Z \leq -A(\rho)$.

(a) Case 1: $\rho < 1$. define

$$\bar{p}_{ij}(t) = e^{-A(\rho)t} p_{ij}(t) \rho^{j-i}, \quad i, j \geq 0, t \geq 0. \quad (12)$$

Then $\bar{P}(t) = (\bar{p}_{ij}(t); i, j \geq 0)$ is a standard and honest transition function. Its q -matrix $\bar{Q} = (\bar{q}_{ij}; i, j \geq 0)$ is given by

$$\bar{q}_{ij} = \begin{cases} i\bar{b}_{j-i+1} + \bar{a}_{j-i}, & \text{if } i \geq 0, j \geq i \\ i\bar{b}_0, & \text{if } i \geq 1, j = i - 1 \\ 0, & \text{otherwise} \end{cases} \quad (13)$$

where $\bar{a}_j = a_j \rho^j - A(\rho) \delta_{0j}$ ($j \geq 0$) and $\bar{b}_j = b_j \rho^j$ ($j \geq 0$). Applying Proposition 1 to \bar{Q} will imply the \bar{Q} -process is recurrent, Hence $\lambda_Z = -A(\rho)$.



(b) Case 2: $\rho = 1$. For any $\varepsilon > 0$, define

$$q_{ij}^{(\varepsilon)} = \begin{cases} ib_{j-i+1}^{(\varepsilon)} + a_{j-i}, & \text{if } i \geq 0, j \geq i \\ ib_0^{(\varepsilon)}, & \text{if } i \geq 0, j = i - 1 \\ 0, & \text{otherwise} \end{cases}$$

where $b_k^{(\varepsilon)} = b_k - \varepsilon\delta_{k1}$. Then $Q^{(\varepsilon)} = (q_{ij}^{(\varepsilon)}; i, j \geq 0)$ is a nonconservative BID q -matrix. Let $P^{(\varepsilon)}(t) = (p_{ij}^{(\varepsilon)}(t); i, j \geq 0)$ be the minimal $Q^{(\varepsilon)}$ -function. It can be proved that $p_{ij}^{(\varepsilon)}(t) \leq p_{ij}(t)$. However, $P^{(\varepsilon)}(t)$ has the decay parameter $\lambda_Z^{(\varepsilon)} = -A(\rho_\varepsilon)$ and hence $\lambda_Z \leq \lambda_Z^{(\varepsilon)} = -A(\rho_\varepsilon)$. Now, letting $\varepsilon \downarrow 0$ yields that $\lambda_Z \leq -A(1)$.

□





Theorem 2. Let Q be defined as in (1) – (2) and $P(t) = (p_{ij}(t); i, j \geq 0)$ be the Feller minimal Q -function and λ_Z be the decay parameter of $P(t)$ on \mathbf{Z}_+ .

(i) If $B'(1) > 0$ then $P(t)$ is λ_Z -positive.

(ii) If $B'(1) \leq 0$ then $P(t)$ is λ_Z -recurrent if and only if

$$\tilde{J} = \int_0^1 \frac{1}{B(s)} e^{\int_0^s \frac{A(y) - A(1)}{B(y)} dy} ds = +\infty. \quad (14)$$

Moreover, $P(t)$ is λ_Z -positive if and only if

$$\int_0^1 \frac{A(1) - A(y)}{B(y)} dy < \infty. \quad (15)$$



Sketch of the proof. Note that if $\rho < 1$ then $(\bar{p}_{ij}(t); i, j \geq 0)$ is recurrent. Also note $\bar{B}(1) = \bar{A}(1) = 0$ together with $\bar{B}'(1) < 0$ and $\bar{A}'(1) < \infty$, applying Proposition 2 to \bar{Q} will yield (i).

Secondly, suppose that $B'(1) \leq 0$ and thus by Theorem 1 we have $\lambda_Z = -A(1)$. Define

$$\bar{p}_{ij}(t) = e^{\lambda_Z t} p_{ij}(t), \quad i, j \geq 0, t \geq 0.$$

Apply Proposition 2 and Theorem 1 to $(\bar{p}_{ij}(t))$, we get (ii). □

Theorem 3. (i) *there exists a λ_Z -invariant measure $(m_i; i \geq 0)$ for Q on \mathbf{Z}_+ , which is unique up to constant multiples. Moreover, $M(s) = \sum_{i=0}^{\infty} m_i s^i$ is given by*

$$M(s) = m_0 e^{\int_0^s \frac{A(\rho) - A(y)}{B(y)} dy}, \quad |s| < \rho \quad (16)$$

where $m_0 > 0$ is a constant.

(ii) *$(m_i; i \geq 0)$ is also a λ_Z -invariant for $P(t)$.*

(iii) *$M(1) = \sum_{i=0}^{\infty} m_i < \infty$ if and only if $B'(1) \leq 0$ and*

$$\int_0^1 \frac{A(1) - A(y)}{B(y)} dy < \infty.$$

(iv) *$(\rho^k; k \geq 0)$ is a λ_Z -invariant vector for $P(t)$ on \mathbf{Z}_+ . Moreover, if $B'(1) > 0$ or $B'(1) \leq 0$ with (14) holds, then $(\rho^k; k \geq 0)$ is the unique (up to constant multiples) λ_Z -invariant vector for $P(t)$ on \mathbf{Z}_+ .*



4 Applications

- Q being conservative.

Theorem 4. *The minimal Q -function is the unique MBPID. Moreover,*

(i) *if $B'(1) \leq 0$, then $\lambda_Z = 0$ and the MBPID is 0-recurrent iff $B'(1) \leq 0$ and $J = +\infty$ where J is given in (5).*

(ii) *If $B'(1) > 0$ then $\lambda_Z = -A(\rho) > 0$. Also, the MBPID is positively λ_Z -recurrent and there exists a unique (up to constant multiples) λ_Z -invariant measure $(m_i; i \geq 0)$ whose generating function $M(s) = \sum_{i=0}^{\infty} m_i s^i$ is given by*

$$M(s) = m_0 \exp\left\{ \int_0^s \frac{A(\rho) - A(y)}{B(y)} dy \right\}, \quad |s| < \rho.$$

Furthermore, this λ_Z -invariant measure is not summable and thus there does not exist any quasi-stationary distribution.



- Q being not conservative.

Theorem 5. (i) *The Feller minimal \tilde{Q} -function is the unique \tilde{Q} -function satisfying Kolmogorov forward equation.*

(ii) *\tilde{Q} is not regular iff $B(1) = 0$ (thus $A(1) < 0$), $B'(1) = +\infty$ and $\int_{\varepsilon}^1 \frac{ds}{-B(s)} < +\infty$ for some (equivalently for all) $\varepsilon \in (\rho, 1)$ where $\rho < 1$.*

(iii) *If \tilde{Q} is regular, then $a_{i\Delta} = 1$ ($i \geq 0$). If \tilde{Q} is not regular, then*

$$a_{i\Delta} = A(1) \cdot \int_{\rho}^1 \frac{y^i}{B(y)} e^{-\int_y^1 \frac{A(x)}{B(x)} dx} dy \quad \text{and} \quad a_{i\infty} = 1 - a_{i\Delta} \quad (17)$$

where $a_{i\Delta}$ and $a_{i\infty}$ are the extinction and explosion probability of the Feller minimal \tilde{Q} -process, respectively.



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