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# Exit Measure of Super-diffusions in Random Medium

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### **Outline:**

1) Introduction of the exit measure of super-diffusions

2) Superdiffusions in random medium

3) Absolute continuity of exit measure  $X_D$ 

4) Regularity of the density of exit measure  $X_D$ 

1. Introduction of the exit measure of Super-diffusions

1) Intuitive definition (Branching Particle Systems)

 $\xi$ : A diffusion in  $\mathbb{R}^d$  with generator L.

Consider a system of particles with undergo random motion and branching on  $\mathbb{R}^d$  according to the following rules:

a). At time t = 0, we have finite number of particles which are distributed according to the law of the Poisson point process on  $\mathbb{R}^d$  with intensity  $n\mu$ . (Each particle has mass 1/n)

b). Each particle survives with probability  $\exp(-nt)$  at time t.

c). At the end of its lifetime, a dying particle gives birth to k offsprings with probability  $p_k^n$ ,  $k = 0, 1, 2, \cdots$ .

d). During its lifetime, the motion of each particle is governed by the process  $\xi$ .

e). All particle's lifetime, motions, and branching are independent of one another.

For a Borel set  $B \in \mathbf{R}^d$ , put

 $X_t^n(B) = rac{1}{n} (\# ext{ of particles which are alive at time } t ext{ and located in } B)$ Suppose D is a domain. For Borel set  $B \in \mathcal{B}(\partial D)$ , put

 $X_D^n(B) = \frac{1}{n} (\# \text{ of particles whose exit point from } D \text{ is in } B).$ 

Under certain conditions (see remark below), it can be proved that as  $n \to \infty$ ,

 $X_t^n \Longrightarrow X_t \quad X_D^n \Longrightarrow X_D \quad (\text{weakly}).$ 

We call  $X = \{X_t, X_D; P_\mu\}$  a super-diffusion (enhanced model).

 $X_t$  describes the mass distribution of particles at time t.

 $X_D$  is called the exit measure from D, which describes the mass distribution of exit points.

**Remark** Main conditions on  $p^n = (p_k^n, k = 0, 1, 2, \cdots)$ :

$$p_k^{(n)}=0$$
 if  $k=1$  or  $k\geq n+1,$ 

and

$$\sum_{k=0}^n k p_k^{(n)} = 1$$
 and  $\lim_{n o \infty} \sup_{k \ge 0} |p_k^{(n)} - p_k| = 0,$ 

where  $\{p_k, k = 0, 1, 2, \dots\}$  is the limiting offspring distribution which is assumed to satisfy following conditions:

$$p_1=0,$$
  $\sum\limits_{k=0}^{\infty}kp_k=1$  and  $m_2:=\sum\limits_{k=0}^{\infty}k^2p_k<\infty.$ 

2) (Dynkin's definition) The Laplace functional of  $X_D$  is given by

$$P_{\mu}\exp(-\langle f,X_D
angle)=\exp(-\langle u,\mu
angle), f\in b\mathcal{B}(\mathrm{R}^d),$$

where u is the unique solution to the following integral equation:

$$u(x) + \int_0^{\tau_D} u^2(\xi_s) ds = \Pi_x \left[ f(\xi_{\tau_D}) 
ight].$$
 (1)

Differential form:

$$Lu=u^2, \hspace{0.3cm}$$
 in  $D,$  $uert_{\partial D}=f(x).$ 

But this method does not work for super-diffusions in a random medium due to interaction between particles, which destroys the multiplicative property:

$$egin{aligned} & P_{\mu_1+\mu_2}\exp(-\langle f,X_D
angle) \ &= & P_{\mu_1}\exp(-\langle f,X_D
angle)\cdot P_{\mu_2}\exp(-\langle f,X_D
angle), \end{aligned}$$

which can be formally written as

$$(X_D, P_{\mu_1 + \mu_2}) = (X_D, P_{\mu_1}) + (X_D, P_{\mu_2})$$
 in law .

It is well-known that the log-Laplace functional technique is based on the multiplicative property.

Question: How to define exit measure  $X_D$  for super-diffusions in random medium.

3) (Le Gall and Mytnik's definition) In Le Gall and Mytnik (2005), the exit measure of a super-Brwonian motion was obtained by an approximation method.

 $B = (B_t, \Pi_x)$ : A Brownian motion in  $\mathbb{R}^d$  starting from x.

 $K_D(x, z)$ : the Poisson kernel of Brownian motion B in D;  $G_D(x, y)$ : the Green function of Brownian motion B in D.

A fact:  $K_D(x, z)$  is half the normal derivative of the mapping  $y \rightarrow G_D(x, y)$  at  $z \in \partial D$ , in other words,

 $G_D(x,y)\sim 2
ho(y)K_D(x,z), \ \ y
ightarrow z$  along the normal direction.

### BM

 $\delta_{B_{t}}$  $\delta_{B_{\tau D}}$  (exit measure):  $\Pi_x \langle \phi, \delta_{B_{ au_D}} 
angle$  $= \int_D K_D(x,z)\phi(z)\sigma(dz)$ Occupation time measure:  $O_D := \int_0^{\tau_D} \delta_{B_t} dt = \int_0^\infty \delta_{\xi_t} dt$  $\langle \Pi_x \langle \phi, O_D 
angle = \int_D G_D(x,y) \phi(y) dy$ 

Super-BM  $X_t$   $X_D$ ( exit measure ) : How to describe  $\langle \phi, X_D \rangle$ ?

 $Y_D := \int_0^\infty X_t^D dt$  $Y_D$  can be described

### Here

$$\xi_t := egin{cases} B_t, & t < au_D, \ & \partial, & t \geq au_D, \end{cases}$$

# $X_t^D$ is the super-Breonian motion in D (with underling motion $\xi$ ).

For every  $\epsilon > 0$  set

$$F_{\epsilon} = \{x \in D; \rho(x, \partial D) \leq \epsilon\}.$$

Then we have

$$egin{aligned} &rac{1}{\epsilon^2}\Pi_x\left[\int_0^\infty I_{F_\epsilon}(\xi_t)\phi(\xi_t)dt
ight] &=& rac{1}{\epsilon^2}\int_{F_\epsilon}G_D(x,y)\phi(y)dy\ & o &\int_{\partial D}K_D(x,z)\phi(z)\sigma(dz). \end{aligned}$$

Suppose  $X = (X_t, t \ge 0)$  is a super-Brownian motion in D. More precisely, the underlying spatial motion  $\xi$  is a Brownian motion killed when it exits D. It is reasonable to have

$$X_D^\epsilon(dy):=rac{1}{\epsilon^2}\int_0^\infty I_{F_\epsilon}(y)X_t(dy)dt\Longrightarrow X_D( ext{ as }\epsilon o 0).$$

### 2. Super-diffusion in random medium (Ren, song and Wang 08)

Suppose that for each  $k \in \mathbb{N}$ ,  $z_k$  is the strong solution of the following equation:

$$\begin{aligned} z_k(t) - z_k(0) &= \int_0^t c(z_k(s)) dB_k(s) \\ &+ \int_0^t \int_{\mathbb{R}^d} h(y - z_k(s)) W(dy, ds), \end{aligned}$$
(2)

where  $\{B_k, k \ge 1\}$  are independent  $\mathbb{R}^d$ -valued, standard Brownian motions, W is a Brownian sheet or space-time white noise on  $\mathbb{R}^d$ .

## Assume that the diffusion matrix $(a_{pq})_{1 \leq p,q \leq d}$ defined by

$$a_{pq}(x) := \sum_{r=1}^{d} c_{pr}(x) c_{qr}(x),$$
 (3)

is uniformly elliptic and bounded on  $\mathbb{R}^d$ . Assume further that  $h = (h_1, \cdots, h_d) \in L^1(\mathbb{R}^d) \cap L^2(\mathbb{R}^d)$ . Put

$$ho_{pq}(x,y) := \int_{\mathbb{R}^d} h_p(u-x)h_q(u-y)du, \quad p,q=1,\cdots,d.$$

### Notations:

 $(\mathscr{D}(A), A)$ : Generator of  $z_1$  killed when it leaves D(denoted as  $\xi$ ). For  $\phi \in \mathscr{D}(A)$ ,

$$A\phi(x)=\sum_{p,q=1}^drac{1}{2}(a_{pq}(x)+
ho_{pq}(0,0))\partial_p\partial_q\phi(x),\quad x\in D.$$
 (5)

 $M_F(D)$ : the set of all finite measures on D;  $M_{F,c}(D) := \{ \nu \in M_F(D) : \operatorname{supp}(\nu) \subset D \}.$   $K_D(x, z)$ : the Poisson kernel of  $\xi$  in D;  $G_D(x, y)$ : the Green function of  $\xi$  in D.

For any measure  $\mu \in M_{F,c}(D)$ , there is a unique solution  $X = (X_t, t \ge 0)$  (called super-diffusion in random medium) to the martingale problem:

$$X_{t}(\phi) - X_{0}(\phi)$$

$$= \sum_{p=1}^{d} \int_{0}^{t} \int_{\mathbb{R}^{d}} \langle h_{p}(y - \cdot) \partial_{p} \phi(\cdot), X_{s} \rangle W(dy, ds)$$

$$+ \int_{0}^{t} \int_{D} \phi(x) M(dx, ds)$$

$$+ \int_{0}^{t} \left\langle \sum_{p,q=1}^{d} \frac{1}{2} (a_{pq}(\cdot) + \rho_{pq}(\cdot, \cdot)) \partial_{p} \partial_{q} \phi(\cdot), X_{s} \right\rangle ds (6)$$

for every t>0 and  $\phi\in C^\infty_c(D)$ , where M is a square-integrable

martingale measure with

$$\langle M(\phi) 
angle_t = \gamma \sigma^2 \int_0^t \langle \phi^2, X_u 
angle du$$
 for every  $t > 0$  and  $\phi \in C_c^\infty(I)$ 

Here

$$M_t(\phi) := \int_0^t \int_D \phi(y) M(ds, dy) \tag{7}$$

is a square-integrable, continuous  $\{\mathcal{F}_t\}$ -martingale, and

$$W_t(\phi):=\sum_{p=1}^d\int_0^t\int_{\mathbb{R}^d}ig\langle h_p(y-\cdot)\partial_p\phi(\cdot),X_sig
angle\,W(dy,ds),$$

 $\mathcal{F}_t := \sigma\{X_s(f), M_s(f), W_s(\phi), f \in \mathcal{B}(D), \phi \in C^1(D), s \leq t\}.$ Moreover,  $W_t(\phi)$  and  $M_t(\phi)$  are orthogonal.

### 3. Absolute continuity of the exit measure $X_D$

Recall that

$$egin{aligned} F_\epsilon &= \{x \in D; 
ho(x, \partial D) \leq \epsilon\}. \ X_D^\epsilon(dy) &:= rac{1}{\epsilon^2} \int_0^\infty I_{F_\epsilon}(y) X_t(dy) dt. \end{aligned}$$

The following theorem provides a stochastic integral representation for the exit measure of a super-diffusion in random medium and its density when it exists.

**Theorem 1** (i) Then for every  $\varphi \in C(D)$ ,

 $\langle arphi, X_D^\epsilon 
angle o \langle arphi, X_D 
angle \ \ \mathbb{P}_\mu - \textit{a.s. and in } L^2(\Omega, \mathbb{P}_\mu),$ 

where

$$egin{aligned} &\langle \phi, X_D 
angle \ &= \langle H_D \phi, \mu 
angle + \int_0^\infty \int_D H_D \phi(x) dM(s,x) \ &+ \sum_{p=1}^d \int_0^\infty \int_{\mathbb{R}^d} \langle h_p(z-\cdot) \partial_p(H_D \phi), X_s 
angle W(dz,ds). \end{aligned}$$

(ii) Suppose d < 3. For every  $y \in \partial D$ , define

$$egin{aligned} &x_D(y)\ &=~\langle K_D(\cdot,y),\mu
angle+\int_0^\infty\int_D K_D(x,y)dM(s,x)\ &\sum_{p=1}^d\int_0^\infty\int_{\mathbb{R}^d}\langle h_p(z-\cdot)\partial_p(K_D(\cdot,y)),X_s
angle W(dz,ds). \end{aligned}$$

Then,  $x_D(y) \ge 0$ ,  $\mathbb{P}_{\mu}$ -a.s. for every  $y \in \partial D$ . Finally,

$$X_D(dy) = x_D(y) \sigma(dy), \hspace{1em} \mathbb{P}_{\mu} - a.s.$$

where  $\sigma$  is the surface measure on  $\partial D$  normalized to have total measure 1.

### 4. Regularity of the density of exit measure

Note that, by definition (4),  $\rho_{pq}(x, x) = \rho_{pq}(0, 0)$ . In this section we assume that  $(a_{pq}(x))_{1 \le p,q \le d}$  does not depends on spacial position x, then

$$A\phi(x) = \sum_{p,q=1}^{d} \frac{1}{2}(a_{pq} + \rho_{pq}(0,0))\partial_{p}\partial_{q}\phi(x), \quad x \in D,$$
 (10)

where  $(a_{pq})_{1 \le p,q \le d}$  is a constant and positive definite matrix.

The next result gives the regularity of the density of  $X_D$  in a random medium.

**Theorem 2** Assume that d = 2 and the underling motion is a diffusion with constant diffusion matrix. For  $\mu \in M_{F,c}(D)$ , the processes  $(x_D(y), y \in \partial D)$  under  $P_{\mu}$  has a continuous version.

Open question: If  $(a_{pq}(x))_{1 \le p,q \le d}$  does depend on spacial position x, does the density  $x_D$  has continuous version?

Put

$$x_D^1(y) = \int_0^\infty \int_D K_D(x,y) dM(s,x),$$

and

$$x_D^2(y) = \sum_{p=1}^d \int_0^\infty \int_{\mathbb{R}^d} \langle \partial_p(K_D(\cdot,y)) h_p(z-\cdot), X_s 
angle W(dz,ds).$$

To prove that  $(x_D(y), y \in \partial D)$  under  $P_{\mu}$  has a continuous version we only need to prove that  $(x_D^1(y), y \in \partial D)$  and  $(x_D^2(y), y \in \partial D)$  under  $P_{\mu}$  have continuous versions separately.

**Lemma 3** There exists a constant C such that, for  $y_1, y_2 \in \partial D$ ,  $\mathbb{P}_{\mu}((x_D^1(y_1) - x_D^1(y_2))^4) \leq C|y_1 - y_2|^2$ . The processes  $(x_D^1(y), y \in \partial D)$  has a continuous version.

### **Proof:**

$$K_{y_1,y_2}(\cdot) := K_D(\cdot,y_1) - K_D(\cdot,y_2).$$

Then

$$x_D^1(y_1) - x_D^1(y_2) = \int_0^\infty \int_D K_{y_1, y_2}(x) dM(s, x).$$
(11)

By the Burkholder-Davis-Gundy inequality

$$\mathbb{P}_{\mu}((x_D^1(y_1)-x_D^1(y_2))^4)\leq C\mathbb{P}_{\mu}\left(\int_0^\infty \langle K_{y_1,y_2}^2,X_s
angle ds
ight)^2.$$

Note that

$$egin{aligned} & \mathbb{P}_{\mu}\left(\int_{0}^{\infty}\langle K_{y_{1},y_{2}}^{2},X_{s}
angle ds
ight)^{2} \ & \leq & Sup \quad G_{D}(K_{D}(\cdot,y_{1})-K_{D}(\cdot,y_{2}))^{2}(x) \ & \quad x\in ext{supp}(\mu) \ & \quad \cdot \ \sup_{x\in D}G_{D}\left[G_{D}(K_{D}(\cdot,y_{1})-K_{D}(\cdot,y_{2}))^{2}
ight](x) \ & \leq & C\left|y_{1}-y_{2}
ight|\cdot\left|y_{1}-y_{2}
ight|. \end{aligned}$$

# **Lemma 4** There exists a constant C such that, for $y_1, y_2 \in \partial D$ , $\mathbb{P}_{\mu}((x_D^2(y_1) - x_D^2(y_2))^4) \leq C|y_1 - y_2|^2$ . The processes $(x_D^2(y), y \in \partial D)$ has a continuous version.

**Proof:** By the Burkholder-Davis-Gundy inequality,

$$\begin{split} & \mathbb{P}_{\mu}((x_{D}^{2}(y_{1})-x_{D}^{2}(y_{2}))^{4}) \\ \leq & C\mathbb{P}_{\mu}\left(\sum_{p=1}^{d}\int_{0}^{\infty}\int_{\mathbb{R}^{d}}\langle\partial_{p}(K_{y_{1},y_{2}})h_{p}(z-\cdot),X_{s}\rangle^{2}dsdz)\right)^{2} \\ \leq & \cdots \\ \leq & C|y_{1}-y_{2}|^{2}+\\ & C|y_{1}-y_{2}|\sup_{\substack{x\in \mathrm{supp}(\mu)\\x\in \mathrm{supp}(\mu)}}|G_{D}\partial_{i}(K_{D}(\cdot,y_{1})-K_{D}(\cdot,y_{2}))(x)| \\ & \cdot\sup_{x\in D}G_{D}|G_{D}\partial_{i}(K_{D}(\cdot,y_{1})-K_{D}(\cdot,y_{2}))|(x) \\ & +C|y_{1}-y_{2}|\sup_{x\in D}G_{D}[G_{D}\partial_{i}(K_{D}(\cdot,y_{1})-K_{D}(\cdot,y_{2}))]^{2}(x) \end{split}$$

**Lemma 5** Assume that d = 2 and A has constant coefficients. For any compact subset K of D and i = 1, 2, we have, for  $z_1, z_2 \in$  $\partial D$ ,

$$\sup_{x \in K} |G_D \partial_i (K_D(\cdot, z_1) - K_D(\cdot, z_2))(x)| \le C |z_1 - z_2|^{1/2};$$

 $\sup\, G_D \left| G_D \partial_i (K_D(\cdot,z_1) - K_D(\cdot,z_2)) 
ight| (x) \leq C |z_1 - z_2|^{1/2};$  $x \in D$ and

 $\sup G_D \left[G_D \partial_i (K_D(\cdot,z_1)-K_D(\cdot,z_2))
ight]^2(x) \leq C |z_1-z_2|.$  $x \in D$ 

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