

# Optimal Ventcel Graphs, Minimal Cost Spanning Trees and Asymptotic Probabilities

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6th Workshop on Markov Processes and Related Topics  
2008, 7.21-26, WuHU, Anhui

Let  $X_n^\epsilon$  be an aperiodic irreducible Markov Chain on a finite set  $S$  with transition function  $p^\epsilon = p_{i,j} \epsilon^{U(i,j)} (1 + o(1))$  where  $0 \leq U(i,j) \leq \infty$  will be referred to as a cost function. We assume  $p_{i,j} = 0$  if  $U(i,j) = \infty$  and let  $\mu^\epsilon$  be the invariant distribution of  $X_n^\epsilon$ . It is well-known that there are constants  $h(i) \geq 0, \beta_i > 0$  such that

- $\lim_{\epsilon \downarrow 0} \mu^\epsilon(i) / \epsilon^{h(i)} = \beta_i$  for any  $i \in S$ .
- Let  $\underline{S} = \{i \in S, h(i) = 0\}$ . (set of minimal states.) Then,

$$E^\epsilon T \approx \epsilon^{\delta_h} \quad \text{for small } \epsilon.$$

Here  $T$  is the hitting time of  $\underline{S}$  and the expectation is from the invariant distribution.

- $E^\epsilon T_i \approx \epsilon^{\delta_v}$  where  $i$  is any fixed state in  $\underline{S}$ .

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The problem we wish to address is to use Ventcel graphs (minimal spanning trees) to describe the constants

$$h(i), \delta_h \text{ and } \delta_v.$$

- All these constants have been discussed before using the so called cycles..
- Conceptually easy through "cycles".
- Hard in real computation.
- $X_n^\epsilon$  does not converge to  $X_n^0$ . Hence a singular perturbation.

Take the Ising model as an example. Let  $u(i)$  be the energy of a state  $i \in S$ . At temperature  $T$ , the probability being at  $i$  is

$$P_T(i) \propto \exp(-u(i)/T) \quad (P_T(i) = 1/Z \cdot \exp(-u(i)/T))$$

where

$$Z = \sum_i \exp(-u(i)/T).$$

In general, it is difficult to find the ground states of this energy landscape. One way to find them using computers is the following.

- To run a Markov chain  $X_n^T$  on  $S$  with transition

$$P_{i,j}^T = p_{i,j} \exp(-(u(j) - u(i))^+) / T, \quad j \in N(i).$$

where  $N(i)$  is a neighborhood system of  $u$  and usually contains very few states.

- $u(j) - u(i)$  is easy to compute. NOT  $u(i)$ .
- $P(X_n^T \in \text{ground states}) \rightarrow 1$  for small  $T$ .
- Example. In the Ising Model,  
 $u(i) = -\sum_{|b-b'|=1} j(b, b') i(b) i(b')$ . Here  $b, b'$  are lattice points and  $i$  is a configuration.  $i(b) = 1$  or  $-1$ .

To be more general, let  $u(i, j)$  be a cost function on  $S \times S$  and let  $W \subseteq S$ .

- **Definition.** A  $W$ -Ventcel graph is a function  $g$  from  $S \setminus W$  to  $S$  with no cycles.
- **Definition.** For a  $W$ -graph  $V(g) = \sum_{i \in S \setminus W} u(i, g(i))$  is called the cost of  $g$ .
- **Definition.** A  $W$ -graph  $g$  is called  $W$ -optimal if  $V(g) \leq V(g')$  for any  $W$ -graph  $g'$ . We use  $v(W)$  for the value  $V(g)$  where  $g$  is  $W$ -optimal
- **Definition.** For any positive integer  $k$ , let  $v(k) = \min\{V(g), g \text{ is a } W\text{-graph with } |W| = k\}$ .

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Our main results are as follows.

- (1)  $h(i) = v(\{i\}) - v_1$
- (2)  $\delta_v = v_1 - v_2$  and
- (3)  $\delta_h = v_{k_0-1} - v_{k_0}$  where  $k_0 = \min\{k :$   
there exists an  $k$  optimal  $W$ -graph with  $W \notin \underline{S}\}$ .

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- For a cost function  $u(i, j)$ , let  $V(i) = \min_{j \neq i} u(i, j)$ .
- For two states  $i, j \in S$ , we say  $i \geq j$  if there exists  $i_0 = i, i_1, \dots, i_m = j$  such that  $u(i_k, i_{k+1}) = v(i)$  for each  $k$ .
- $i$  is minimal if  $i \geq j$  implies  $j \geq i$ .
- Two different states  $i, j$  are said equivalent if  $i \geq j$  and  $j \geq i$  and  $i, j$  are minimal. Each equivalent class is called a "cycle".



Let  $S^0 = S$ ,  $u^0 = u$  and  $V^0 = V$ . Let  $S^1 =$  all cycles of  $S^0$ . Hence if  $C^1 \in S^1$ , then  $C^1 = \{C_i^1\}_i$  where  $C_i^1 \in S^0$ . Let the depth of  $C^1$  be defined as  $d(C^1) = \max\{V^0(C_i^1) : C_i^1 \in C^1\}$ .

- **Definition.**

$$u^1(C^1, \bar{C}^1) = d(C^1) + \min_{i,j} \{u^0(C_i^1, \bar{C}_j^1) - V^0(C_i^1)\}.$$

- $S^1$ ,  $u^1$  and  $V^1$  forms a new cost function where  $V^1(C^1) = \min u^1(C^1, \bar{C}^1)$ ,  $\bar{C}^1 \neq C^1$ .

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- The process will end at some  $N$ .
- For each state  $i \in S$ , there will be a sequence of cycles  $i = C^0 \in C^1 \in C^2 \in \dots \in C^N$ . (The family tree of  $i$ .)

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The constants can be defined as follows.

- $\underline{S} = \{i \in S, h(i) = 0 \text{ where } h(i) = \sum_n d^n(C^{n+1}) - V^n(C^n)\}$ .
- $\delta_h = \max\{V^k(C^k), C^k \in S^k, C^k \cap \bar{S} = \phi\}$ .
- $\delta_v = \max\{V^k(C^k), C^k \in S^k, i_0 \notin C^k\}$  where  $i_0 \in \underline{S}$  is fixed.

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